# INSTRUCTION MANUAL

AUTO GENERATOR CONTROLLER

<u>AGC-300-0</u>

 $\bigcirc$  DAIICHI ELECTRONICS CO., LTD.

# Introduction

Thank you for your purchase of our product.

Please read this instruction manual carefully before installation, wiring, and using this product. Please keep you in custody at hand to be found any time after it was read.

# Safety precaution

#### 1. Operating/storage environment

Do not install or store this product under below-mentioned environment. Damage caused by the product usage beyond specified environment leads to repair (not free of charge) even under warranty period.

- ① Ambient temperature: below -10 or over +55℃. Humidity: over 90% RH.
- O Places where corrosive gas is generated (SO2 / H2S / etc.)
- ③ Places where dust is generated.
- ④ Places with much vibration and shock.
- ⑤ Places with noise from the outside.

#### 2. Installation, electrical wiring

Only technical expert can install or perform electrical wiring work following below-mentioned safety precaution along with referring to instruction manual.



① Perform connection with connection diagram. Inappropriate connection causes product damage, burnout, fire (Example: High voltage generation on the secondary side of CT).
 ② Hot-line job is prohibited to prevent electrical shock, product damage, burnout, fire and gas

② Hot-line job is prohibited to prevent electrical shock, product damage, burnout, fire and gas explosion.

shock ③ Never fail to install terminal cover after work for electrical shock prevention.

Install this product to panel by tightening screw of installation tool using plus screwdriver(Tightening torque 0.2 to 0.29N·m). If torque wrench is not kept handy, rotate this product approximately 360 degree after contacting both screws to panel, then make sure that this product is fixed firmly.

## 3. Setting

This product is set up by next initial value at factory shipment.

Please make a setting change, if it does different usage from an initial setting value. (5. section, 13 page to 19 page) In addition, about a rated frequency, it is shipped by the designated set value.

## 4. Use

① Please use input within rated range. Use outside rated range has caused failure of a device.

② Please shut a switch cover other than the case of operation.



Please keep in mind that it will receive an electric shock if a terminal is touched into an energization.
 Please keep in mind that it separates from the object of a guarantee if this product is disassembled and converted without notice. And, since failure of a device, a fire, etc. occur by reconstruction etc., it is dangerous. Please inform our company of specification change etc.

## 5. Maintenance, inspection

① Wipe off the surface of the unit with a dry soft cloth. If the display name plate stuck on the body is rubbed strongly, a character may disappear. Please do not use solvent, cleaner, alcohol, chemical for cleaning.

- ② Please check the next item.
  - Isn't there any damage in the appearance of a product?
  - Does indication correspond to the input?
  - Isn't there any slack in the connection of mounting and a terminal stand? (Please carry out in the state of blackout.) If an unknown thing occurs, please check to our company.

# 6. Transportation

Please pack up with shock absorbing material. In order to heighten a buffer effect, please stuff shock absorbing material into all crevices firmly. Failure by the shock in transportation should not occur.

## 7. The other

- This product does not use a mercury part and a nickel-cadmium battery.
- @ The discarded product. If the burns up this product, it gives bad influence to environment.

# Content

1. Pr 1.1 1.2 1.3	oduct explanatory Use ····· Features ····· Function ····	3 3 3
2. Sp 2. 1 2. 2 2. 3	ecification Type and specification code Input, output, display Performance	3 4 5
3. Ha 3. 1 3. 2 3. 3 3. 4 3. 5 3. 6 3. 7	ndling Outline drawing Installation Control wiring reference drawing of power receiving and plural generators Block diagram of input and output Connection diagram Cautions on connections Cautions on operation	6 7 8 8 10 10
4. Di 4. 1 4. 2 4. 3	splay The name and function of each part Measurement value display Turn off the light of display	11 11 12
5. 0p 5. 1 5. 2 5. 2 5. 2 5. 2 5. 3 5. 4	eration / setting The name and function of each part Setting .1 Setting of slide-switch .2 Change of the set value by the key switch Caution on setting Setting item list	13 14 15 16 17
6. Co 6. 1 6. 2 6. 3 6. 4 6. 5 6. 6	ntrol function Synchronous closing control Power control Rated frequency control Generator power factor constant control Reactive power proportional distribution control Rated voltage control	19 21 27 28 29 31
7. Op 7. 1 7. 2 7. 3 7. 4	eration outline Before control start Synchronous closing control Distribution control Control example of operation quantity	32 32 33 34
8. Ma 8. 1 8. 2 8. 3 8. 4	intenance Error message ••••••••••••••••••••••••••••••••••••	43 47 49 49

- 1. Product explanatory
- 1.1 Use

Arrangement for controlling electric generator (AGC-300-0□) is the arrangement for controlling electric generator of multifunctional set type which carried each function etc.

(Function: Synchronous closing, Load distribution, Operation quantity control, Loaded condition monitor)

It is the high product of flexibility which can correspond to all needs. This equipment should use continuous power generating system and emergency generator system and cogeneration system.

- 1.2 Features
  - Maximum of 8 system configurations is freely possible for an operation quantity. And, an operation quantity can extend a maximum of 8 sets easily.
  - Efficient operation of a generator is possible. (Heavy burden operation mode)
  - The change of a control value is possible by daytime / night, or a weekday/holiday.
  - Setting change is easy. Stable operation put together with the system is realized.
  - For the purpose of laborsaving, it can correspond to all needs broadly.
  - It contributes to reduction of system total cost.
  - Ac input is withstand voltage AC2000V design.

1.3 Function

- Synchronous closing control
  - Speed matcher function.
  - ② Voltage balance function.
  - ③ Synchronous closing function.
  - ④ Synchronous detection display function.
  - (5) Check relay output (Phase difference  $\pm 15^\circ$  ) function.
  - <sup>©</sup> Phase difference delay detection function.
  - O Synchronous closing direction change function. (FAST/FREE/SLOW)
  - B Frequency range outside detection function.
  - (9) Voltage range outside detection.
- Power control and operation quantity control
  - ① Starting detection function.
  - ② Separation detection function.
  - ③ Operation mode (heavy burden operation or power receiving constant operation) designation function.
  - ④ Power receiving constant control value change function.
  - ⑤ Receiving power average control function.
  - © Generator starting and separation control value change function.
  - ⑦ Interruption starting function.
  - B Forced separation function.
  - (9) Governor system abnormality detection function.
  - ① Frequency range outside detection function.

• Generator power factor constant control.

- ① Power factor control dead band change function.
- O Power factor control cut function at light-load.
- $\textcircled{\sc 3}$  AVR system abnormality detection function.
- ④ Voltage range outside detection function.
- Rated frequency control.
- Rated voltage control.
- 2. Specification
- 2.1 Type and specification code

AGC-300-0(1)					
Туре	Specification	code			

(1) Auxiliary power supply

Symbol	Auxiliary power supply
0	AC100/110V 50/60Hz DC100/110V
1	DC24V

2.2 Input, output, display

No.	ltem	Description	Specification
		Parallel operation of power receiving and generator	Receiving power constant + Generator power proportional distribution + Quantity control / Generator power-factor
1	Operation method	Only a generator operation.	Generator power proportional distribution + Rated frequency control + Quantity control / Generator reactive power proportional distribution + Rated voltage control
2	Bus single-phase input	For voltage, frequency, phase measurement	AC110V, 50/60Hz, 0.5VA
3	Generator 3-phase input	For voltage, power, reactive power, frequency, power factor measurement	АС110V, АС5А, ЗФ, 50/60Hz, Each 0.5VA
4	DC input	Receiving power measurement (With external transducer)	DC4~20mA (About 50Ω) /0~200W (AC110V, 5A, 50/60Hz)
5	Input for control (8 circuits)	Control start Power receiving start Synchronous start Distribution start Offering start Forced separation Lead generator designation Control change	( <sup>1</sup> ) Voltage input DC24V (Operation current 10mA)
6	Output for control (10 circuits)	Start command Separation command Light trouble 90R (AVR increase signal) 90L (AVR decrease signal) 65R (Governor increase signal) 65L (Governor decrease signal)	1a contact photo MOS relay output . (There is polarity, minus common) MAX. DC24V, 90mA
		Synchronous check	1a contact photo MOS relay output MAX. DC24V, 100mA or DC110V, 50mA
7	Communication	Communication to other controller	RS-485
8	Auxiliary power supply	Auxiliary power supply of AGC-300	AC100/110V (85~127V) 50/60Hz Below 10VA, and DC100/110V (80~143V) Below 9W, for both AC and DC uses. Or DC24V (20~28V) Below 9W. Can be specified.
		Address	Digital switch
9	Switch	Set value input / measurement display Set value registration Digit shift Set value increase Display change	Push switch
9	UWI LUI	Function change (ALS/APFR/ALS+APFR)Generator heavy burden (ON/OFF)Power receiving control change (MODE1/MODE2)Generator control change (MODE1/MODE2)Closing direction change (FAST/FREE/SLOW)Set change (ON/OFF)	Slide switch
		ITEM CODE	2 digit 7 segment LED (Orange)
10	Display	MEAS·SET DATA	4 digit 7 segment LED (Orange), LED×2 (Orange)
10		Phase difference display	$LED \times 24$ (Yellow), $LED \times 1$ (Green)
		Status display	LED×10 (Green), LED×1 (Yellow), LED×2 (Red)

Note(<sup>1</sup>) An external relay should use the relay for very small signals which satisfies the designated voltage and current. Note(<sup>2</sup>) The external relay for 25 closing command and a synchronizing check output should use the relay with a surge absorber.

# 2.3 Performance

ltem			Specification				
Voltage difference			±0.5% % for rated voltage				
	Synchronous	Frequency difference	±0.03Hz				
	closing	Closing phase	±5°				
		Receiving power	+1.0% % for maximum power				
		detection accuracy	(Maximum power setting, 1/2 of transducer full scale $\sim$ full scale.)				
		Power detection accuracy	$\pm 1.0\%$ % for rated power				
Accuracy		Reactive power detection accuracy	$\pm 1.0\%$ % for rated reactive power				
	Distribution control	Power-factor detection accuracy	$\pm 3^\circ$ (Load current:more than 10%, Power-fact	or:LEAD 0.5~1~LAG 0.5)			
		Current detection accuracy	±1.0% % for retad current				
		Frequency detection accuracy	±0.1% % for rated frequency				
		Voltage detection accuracy	±1.0% % for rated voltage				
	Common	Pulse width	$\pm 10\% \pm 0.1$ s % for set value				
	Control delay time		$\pm 10\% \pm 0.1$ s % for set value				
	Influence of temperature		In accuracy at 23±20°C.				
Charac-	Influence of voltage		In accuracy at his voltage and generator voltage	$10 \text{ ACREV} \sim 126 \text{ V}$			
teristic			In accuracy at $\Delta C100/110V$ ( $\Delta C85 \sim 127V$ ) DC100/110V (DC80~143V) DC24V (DC20				
	Influence of power supply voltage		~28V).				
	other		Conformity to JIS C 1111: 1989				
	Over-voltage	ACTOD/110V power	2 times to seconds, 1.2 times continuation of r	aleu vollage.			
		supply	1.5 times 10 seconds, 1.2 times continuation of rated voltage.				
	strength	DC100/110V power supply	1.5 times 10 seconds of rated voltage. DC143V continuation.				
	Over everent	AC input	40 times 1 second, 1.2 times continuation of ra	ited current.			
	strength	DC input	2 times 10 seconds, 1.2 times continuation of rated current.				
			(Output signal of transducer)				
			Between electric circuit and case (earth).				
			Bus voltage input, generator voltage input,	Above 2010 at DCE00V			
	Insulation resistance		peneralor current input, power supply input, DC input input for control governor control	MDOVE SUMS2 at DCSUUV			
			output. AVR control output, other control	1108801			
Strength			outputs, communication, each mutual interval.				
			Between electric circuit and case (earth).				
			Bus voltage input, generator voltage input,				
			generator current input, power supply input,	AC2000V 50/60Hz 1 minute			
	Withstand vol	tage	DC input, input for control, output for control,				
			communication, each mutual interval.				
			other control outputs, each mutual interval.	AC500V 50/60Hz 1 minute			
	Impulse withs	tand voltage	Between electric circuit and case (earth).	5kV 1.2/50μs Positive and negative polarity, for each 3 times			
	Shock		294m/s <sup>2</sup> , X, Y, Z direction for each 3 times.				
	Vibration		16.7Hz Double amplitude 1mm, X, Y, Z direction	n for each 2 hours.			
Operatin	g temperature	and humidity range	-10 $\sim+55^\circ\!\mathrm{C}$ , 30 $\sim\!85\%$ RH (Non condensing)				
Storage	temperature ra	nge	-25~+70°C				
Color of	case		Black (Munsell N1.5)				
Mass			Approx. 1.3kg				
Installa	tion		Panel side installation				

Handling
 1 Outline drawing





( Dimension of continuous installation )



Please establish other devices and space distance over 50mm in consideration of radiation by the natural convection of air. And, please secure a space over 50mm with each field in the board (upper, under, side).

#### 3.2 Installation

 $\odot$  Slide installation tool to front direction and remove installation tool from AGC-300.

② Install AGC-300 to installation hole of panel.

③ Install the installation tool to protrusion part of both sides of AGC-300 case and slide toward terminal.

- $\textcircled{\sc 0}$  Tighten the screw of installation tool with plus screwdriver.
  - Tightening torque.∶ 0.20∼0.29N•m

If torque wrench is not kept handy, rotate this product approximately 360 degree after contacting both screws to panel, then make sure that this product is fixed firmly.



3.3 Control wiring reference drawing of power receiving and plural generators



#### 3.4 Block diagram of input and output



- Note(3) It can correspond to the auxiliary power supply DC100/110V. AC100/110V (50/60Hz), or DC24V.
- Note(<sup>4</sup>) The input sensitivity of the transducer for power receiving measurement is a standard ( $0\sim200W$ ). By measurement and the control range, if there is the want of extending a measuring range, please use  $0\sim500W$ 
  - (or O~1kW).
- Note(<sup>5</sup>) COM2, COM3, COM4 are minus common.



<Caution> The relay for 25 closing command and a synchronizing check output should use the relay with a surge absorber.

■ The connection method between controls is shown the following. (4 sets of examples)



- (1) The communication TRXP between each controller and TRXN(s) are connected in twisted pair wire with a shield. as shown in the above figure.
- (2) One shielding wire of twisted pair wire with a shield is connected to the frame ground (F. G.) of controllers. (The above figure ④)
- (3) The controllers (at the above figure, they are ① and ④) of both ends should connect TRXN and TRXT.
- (4) The order of a controller and the address number of the above figure are not related.
- Connector arrangement drawing

Conformity connector { HIF3BA-50D-2.54C (For crimp contact)

DI/DO Terminal name	No.		No.	DI/DO Terminal name	
NC	50		49	NC	
Control start	48		47	Control start	
Power receiving start	46		45	Power receiving start	
Synchronous start	44	48 •• 47	43	Synchronous start	
Distribution start	42	46 1 45	41	Distribution start	DI
Offering start	40		39	Offering start	וט
Forced separation	38		37	Forced separation	
Lead generator designation	36		35	Lead generator designation	
Control change	34		33	Control change	
COM1	32		31	COM1	
NC	30		29	NC	
NC	28		27	NC	
NC	26		25	NC	
NC	24		23	NC	
Start command	22		21	Start command	
Separation command	20	6 5	19	Separation command	
Light trouble	18	4 1 3	17	Light trouble	
COM2	16		15	COM2	
90R	14		13	90R	DO
90L	12		11	90L	DO
СОМЗ	10	HIE384-5084-2 54D	s 9	СОМЗ	
65R	8		7	65R	
65L	6		5	65L	
COM4	4	ι ιυ., LID.	ر 3	COM4	
NC	2		1	NC	

The terminal of a same name is connected inside. Even if it does not wire both of terminals, a problem does not have (good only at single-sided wiring).

3.6 Cautions on connections

- Please install a terminal cover, after connection is completed.
- This equipment has sufficient noise-capacity. However, if a large noise can be thought of, please separate wiring of each input and output (AC input, auxiliary power supply input, DC input, input for control, output for control). It becomes the effective malfunction preventive measures to exogenous noise.
- In order to advance the shield effect, please earthing frame grand terminal (F.G.). And, please give the grounding resistance between a frame grand terminal (F.G.) and the ground as less than 100Ω.
- 3.7 Cautions on operation
  - (1) Caution at the case of an operation start.
    - •Please apply auxiliary power supply after establishing voltage. If power-supply voltage goes up gradually, a malfunction may be done in power supply unstable area.
    - •The address of a controller is read and decided at the case of auxiliary power supply apply.
    - Therefore, please check the address of controller before auxiliary power supplies apply.
    - If the address is changed after a auxiliary power supply apply (in operation) :
    - Auxiliary power supply is turned off after change.  $\rightarrow$  Again, auxiliary power supply is applied.  $\rightarrow$  It is re-set up.

(2) Caution in operation.

- •The controller contained in an operation quantity should apply auxiliary power supply constantly.
- ·If it does not change set value, the setting switch is OFF. If it is used with the setting switch ON, set value mistaken writing (control is abnormal) may occur.

(3) Caution about input, output signal.

- •The input for control is DC24V (input resistance 2.4k $\Omega$ ). The operating current at the case of rated voltage input is about 10mA. If it uses a relay for the input for control, please use the relay for very small current.
- If it operates an external relay by the control output, please use the relay with a surge killer (in order to mitigate the influence of noise).

In addition, the common mode noise-capacity of the contact output of controller is  $1\mu s$  square wave noise  $\pm 1000V$ .

4. Display

## 4.1 The name and function of each part





ALARM : The light is put on at the case of alarm occurrence (Memory error, Synchronous closing mistake, etc.).

4.2 Measurement value display

(1) Change of display item by DISPLAY key.

— ② Control status display

- △V : At the case of synchronous control:
   A voltage difference turn on a light within a closing allowance voltage difference.
   At the case of distribution control:
   The light is put on within a dead band to rated voltage.
- freqency.  $\Delta \rm WI$  : The light is put on within a receiving power dead band.
- $\Delta \text{WG}$  : The light is put on within dead band of generator power distribution
- $\Delta \Phi$  : At the case of synchronous control :
  - The light is put on within (synchronizing check) 15° of phase difference.
    - At the case of power-factor control:
    - The light is put on within a dead band.

## - ③ MEAS·SET DATA display.

The  $\left(\frac{\text{MEAS}}{\text{SET}}\right)$  key changes measurement mode and setting mode.

Item code No. and data are displayed in each mode.

 — ④ Synchronous detection (Phase difference) display.
 ▼ of center is 0° of phase difference.

To center, left side is SLOW and right side is FAST. LED is turn on a light at intervals of 15° of phase difference.

(6) Switching and change of measurement data / setting data It is the key switch of a display change and set value change. (Display change of measurement data, display change of setting data, set value change of setting data) 5 key switches are operated and performed.

If the [DISPLAM] key is pressed from synchronous or distribution control, the display of a measurement value is possible.

Whenever indicated value presses the user is done to the following order. The contents of a display are distinguished by the code.

	oray ilem al synchronous control.						
Code	Display description	Unit					
01	Bus voltage						
02	D2 Bus frequency						
04	Generator voltage	٧					
09	Generator frequency	Hz					
10	Voltage difference	%					
11	Frequency difference	Hz					
13	Device address	_					

• Display item at synchronous control.

The above contents of a display are displayed in order of codes  $01{\sim}13$  (rotation).

## • Display item at distribution control.

Code	Display description	Unit						
03	Receiving power	kW						
04	Generator voltage	٧						
05	Generator current	Α						
06	Generator power	k₩						
07	Generator reactive power	kvar						
08	Generator power factor	%						
09	Generator frequency	Hz						
12	Power receiving average power	k₩						
13	Device address	—						

The above contents of a display are displayed in order of codes 03. to13 (rotation).

- (2) Caution about a measurement value display
   By the relation which gives priority to control processing, there is an item which stops measurement by the control
   state. Please keep in mind that the applicable item holds the value at the time that control changes.
   At synchronous control ····· Item 05 Generator current, Item 06 Generator power.
   Item 07 Generator reactive power, Item 08 Generator power-factor
   At distribution control (Other than the synchronous control) ····· Item 10 Voltage difference,
   Item 11 Frequency difference
- (3) Change of display item by change of item code. (Set change switch: OFF) By changing an item code from synchronous or distribution control, the display of a measurement value and set value is possible. The display of the item code 0~79 is possible.



4.3 Turn off the light of display

(1) Turn off the light of display by key grabbing.

The DISPLAY key is turn off the light by pushing for about 3 seconds.

(2) Automatic displays turn off the light.

A display is turn off the light if there is no key operation within a time which was set up. Set value is based on the set value of the display lights-out of the item code 79. 5. Operation / setting

5.1 The name and function of each part



The address of a controller is set up.

# 5.2 Setting 5.2.1 Setting of slide-switch

4 5 6 2 1 8 ADDRESS       Image: Set Value / Set V							
4 5 6 2 1 8 ADDRESS       SET       Image: Set Control Receive Generator Differition       Image: Set Control Receive Generator Differition         4 5 6 2 1 8 ADDRESS       Image: Set Control Receive Generator Differition       Image: Set Control Receive Generator Differition       Image: Set Control Receive Generator Differition         ADDRESS       Image: Set Control Receive Generator Differition       Image: Set Control Receive Generator Differition       Image: Set Control Receive Generator Differition         Image: Set Control Receive Generator Differition       Image: Set Control Receive Generator Control Set Control Receive Generator Control Receive Generator Control Set Control Receive Generator Control Set Con	$\Delta I S \pm \Delta P F R$						
4 0 6 7 2 18       FUNCTION LOAD RECEIVE GENERATOR DIRECTION SET       Image: Control of the							
2       18         ADDRESS       ALS         APRR       Image: Superson of the second se	MODE 1						
ADDRESS AFFR - OFF WODE2 WODE2 SLOW OFF C	MODE 1						
© Sat change switch							
7 $1$ $2$ $3$ $4$ $5$ $6$ $3$ $4$ $5$ $6$	1						
The closing direction circuit-changing switch can be changed in the synchronous start input O The address circuit-changing switch can be changed in the power-supply input OFF. It is not set in case it performs to other timing. Please do not make an address switch into a middle position. It becomes the cause of switch failure. Please stop doing between 1 and 2, as shown in a figure. Please set the slide-switch as the right position of the both ends or the center. If a switch is stopped in an intermediate position, this product may malfunction (or fa	DFF. $3 \\ 2 \\ 1$ i lure).						
<ul> <li>① Function change switch.</li> <li>The function of distribution control is set up.</li> <li>ALS ······· Power distribution control is performed.</li> <li>APFR ······ Generator power-factor control is performed.</li> <li>ALS+APFR ····· Power distribution and generator power-factor control are performed.</li> </ul>							
② Heavy burden change switch. ON/OFF of generator heavy burden control is set up.							
・Control change switch. (3 points ③~⑤) Switching is performed by ON/OFF of control change input.							
③ Power receiving mode change switch. The mode 1 has not switching with set value ①. The mode 2 performs set value ①→② switching control at the case of control change input ON.							
<ul> <li>④ Generator mode change switch. The mode 1 has not switching with set value ①.</li> <li>The mode 2 performs eat value ①.</li> </ul>							
④ Generator mode change switch. The mode 1 has not switching with set value ①. The mode 2 performs set value ①→② switching control at the case of control change input ON.							
<ul> <li>④ Generator mode change switch. The mode 1 has not switching with set value ①. The mode 2 performs set value ①→② switching control at the case of control change input ON.</li> <li>⑤ Closing direction change switch. In the combination of the closing direction changeover switch and control change input, as shown in</li> </ul>	n the following table,						
<ul> <li>④ Generator mode change switch. The mode 1 has not switching with set value ①. The mode 2 performs set value ①→② switching control at the case of control change input ON.</li> <li>⑤ Closing direction change switch. In the combination of the closing direction changeover switch and control change input, as shown in the closing direction at the case of synchronous control can be designated.</li> </ul>	n the following table, ⊐						
<ul> <li>④ Generator mode change switch. The mode 1 has not switching with set value ①. The mode 2 performs set value ①→② switching control at the case of control change input ON.</li> <li>⑤ Closing direction change switch. In the combination of the closing direction changeover switch and control change input, as shown in the closing direction at the case of synchronous control can be designated. Closing direction change switch Closing direction change switch Control change input (DI)</li> </ul>	n the following table, ]						
<ul> <li>④ Generator mode change switch. The mode 1 has not switching with set value ①. The mode 2 performs set value ①→② switching control at the case of control change input ON.</li> <li>⑤ Closing direction change switch. In the combination of the closing direction changeover switch and control change input, as shown in the closing direction at the case of synchronous control can be designated. Closing direction change switch Closing direction change switch (Slide switch)</li> </ul>	n the following table, ]						
<ul> <li>④ Generator mode change switch. The mode 1 has not switching with set value ①. The mode 2 performs set value ①→② switching control at the case of control change input ON.</li> <li>⑤ Closing direction change switch. In the combination of the closing direction changeover switch and control change input. as shown in the closing direction at the case of synchronous control can be designated. Closing direction change switch Closing direction change switch Closing direction change switch Control change input (DI) (Slide switch) FAST Random FAST</li> </ul>	n the following table, 						
<ul> <li>④ Generator mode change switch. The mode 1 has not switching with set value ①. The mode 2 performs set value ①→② switching control at the case of control change input ON.</li> <li>⑤ Closing direction change switch. In the combination of the closing direction changeover switch and control change input, as shown in the closing direction at the case of synchronous control can be designated. Closing direction change switch</li></ul>	n the following table, 						
<ul> <li>④ Generator mode change switch. The mode 1 has not switching with set value ①. The mode 2 performs set value ①→② switching control at the case of control change input ON.</li> <li>⑤ Closing direction change switch. In the combination of the closing direction changeover switch and control change input, as shown in the closing direction at the case of synchronous control can be designated. Closing direction change switch</li></ul>	n the following table, 						
<ul> <li>④ Generator mode change switch. The mode 1 has not switching with set value ①. The mode 2 performs set value ①→② switching control at the case of control change input ON.</li> <li>⑤ Closing direction change switch. In the combination of the closing direction changeover switch and control change input, as shown in the closing direction at the case of synchronous control can be designated. Closing direction change switch Control change input (DI) (Slide switch) OFF ON FAST Random FAST FREE FAST SLOW SLOW Random SLOW (Caution) Control change input serves as ③~⑤ common use. Therefore, a distribution control ON/OFF of the closing direction switching. Set value may consider as start command OFF. Please prepare holding circuit external</li> </ul>	n the following table.  value also changes by ally.						
<ul> <li>④ Generator mode change switch. The mode 1 has not switching with set value ①. The mode 2 performs set value ①→② switching control at the case of control change input ON.</li> <li>⑤ Closing direction change switch. In the combination of the closing direction changeover switch and control change input, as shown in the closing direction at the case of synchronous control can be designated. Closing direction change switch Closing direction change switch SLOW Closing direction change input serves as ③~⑤ common use. Therefore, a distribution control ON/OFF of the closing direction switching. Set value may consider as start command OFF. Please prepare holding circuit externation © Set change switch. Setting change is possible (ON) or setting change is impossible (OFF), it changes.</li> </ul>	n the following table.  value also changes by ally.						
<ul> <li>④ Generator mode change switch. The mode 1 has not switching with set value ①. The mode 2 performs set value ①→② switching control at the case of control change input ON.</li> <li>⑤ Closing direction change switch. In the combination of the closing direction changeover switch and control change input, as shown in the closing direction at the case of synchronous control can be designated. Closing direction change switch Closing direction change switch Closing direction change switch Closing direction change switch Closing direction change switch RAST RAST REE FAST SLOW Caution&gt; Control change input serves as ③~⑤ common use. Therefore, a distribution control ON/OFF of the closing direction switching. Set value may consider as start command OFF. Please prepare holding circuit externation Set value may consider as start command OFF. Please prepare holding circuit externation Set change is possible (ON) or setting change is impossible (OFF), it changes.</li> <li>⑦ Address change switch. The address of controller is set up.</li> </ul>	n the following table,  value also changes by ally.						
<ul> <li>④ Generator mode change switch. The mode 1 has not switching with set value ①. The mode 2 performs set value ①→② switching control at the case of control change input ON.</li> <li>⑤ Closing direction change switch. In the combination of the closing direction changeover switch and control change input, as shown in the closing direction at the case of synchronous control can be designated. Closing direction change switch Control change input (DI) (Slide switch) 0FF 0N FAST Random FAST FREE FAST SLOW Caution&gt; Control change input serves as ③~⑤ common use. Therefore, a distribution control ON/OFF of the closing direction switching. Set value may consider as start command OFF. Please prepare holding circuit externation Set value may consider as start command OFF. Please prepare holding circuit externation Set value switch. Set change switch. Set change switch. The address of controller is set up. (Caution&gt; About switch middle position. The switch middle position of ②, ③, ④, ⑤ is as follows.</li> </ul>	n the following table, value also changes by ally.						
<ul> <li>④ Generator mode change switch. The mode 1 has not switching with set value ①. The mode 2 performs set value ①→② switching control at the case of control change input ON.</li> <li>⑤ Closing direction change switch. In the combination of the closing direction changeover switch and control change input, as shown in the closing direction at the case of synchronous control can be designated. Closing direction change switch Closing direction switch FAST Random FAST FREE FAST SLOW (Caution) Control change input serves as ③~⑤ common use. Therefore, a distribution control ON/OFF of the closing direction switching. Set value may consider as start command OFF. Please prepare holding circuit externation Set value may consider as start command OFF. Please prepare holding circuit externation Set change switch. Set change switch. The address of controller is set up. (Caution) About switch middle position. The switch middle position of ②, ③, ④, ⑤ is as follows. LOAD RECEIVE RENERATOR DIRECTION</li> </ul>	n the following table, 						
<ul> <li>④ Generator mode change switch. The mode 1 has not switching with set value ①. The mode 2 performs set value ①→② switching control at the case of control change input ON.</li> <li>⑤ Closing direction change switch. In the combination of the closing direction changeover switch and control change input. as shown in the closing direction at the case of synchronous control can be designated. Closing direction change switch Closing direction system SLOW Claution&gt; Control change input serves as ③~⑤ common use. Therefore, a distribution control ON/OFF of the closing direction switching. Set value may consider as start command OFF. Please prepare holding circuit externation Setting change is possible (ON) or setting change is impossible (OFF), it changes.</li> <li>⑦ Address change switch. The address of controller is set up. (Caution&gt; About switch middle position. The switch middle position of ②, ③, ④, ⑥ is as follows. LOAD RECEIVE RENERATOR DIRECTION ON MODE 1 MODE 1 ON</li> </ul>	n the following table. use also changes by ally.						
<ul> <li>④ Generator mode change switch. The mode 1 has not switching with set value ①. The mode 2 performs set value ①→② switching control at the case of control change input ON.</li> <li>⑤ Closing direction change switch. In the combination of the closing direction changeover switch and control change input. as shown in the closing direction at the case of synchronous control can be designated. Closing direction change switch Closing direction switching SLOW Caution〉 Control change input serves as ③~⑤ common use. Therefore. a distribution control ON/OFF of the closing direction switching. Set value may consider as start command OFF. Please prepare holding circuit externa ⑤ Set change switch. Setting change is possible (ON) or setting change is impossible (OFF). it changes.</li> <li>⑦ Address change switch. The address of controller is set up. (Caution〉 About switch middle position. The switch middle position. CloAD RECEIVE RENERATOR DIRECTION ON ON ON OFF OFF NODE 1 NODE 1 NODE 1 NODE 2 OFF NODE 2 OFF NODE 2 OFF NODE 2 OFF</li> </ul>	n the following table. use also changes by ally.						

5.2.2 Change of the set value by the key switch

After switching ON of setting changeover switch, it is possible of change of set value by pressing the  $\frac{MEAS}{SET}$  key. Display and set value change of the item codes 20~79 are possible.



(An example) Item code 33. The power receiving maximum power WRI is changed into initial value 600→800.

- (1) A setting changeover switch (slide switch) is set to ON.  $\rightarrow$  Set permission.
- (2) Push MEAS SET key. (Turn on the light of SET LED, turn off the light of MEASURE LED) The 1 digit of an item code is blinking.

(3) Selection of item code

```
||D| key:Digit shift, |\Delta| key:Numerical setting. The item code 33 is selected.
```

- (4) Next, push USPLAY key. The 4th digit of a set value display is blinking.
- (5) Setting of set value. (It changes into 600→800)
   Push key (digit shift). It shifts blinking to the 3 digits.
   Push key (Numerical setting) two times. It changes into 800.
- (6) The ENTRY key is pushed if setting change is an end. If set value is a range error, it returns to the value before setting change. Please set up again after checking the range.
- (7) Other setting changeing. : Flashing is shifted to an item code by the [IISPLAY] key. (3) section or subsequent ones is repeated.
- (8) All setting is completed. The  $\frac{MEAS}{SET}$  key is pushed and the update of data is done.

If updated normally, "**Yood**" during about 2 seconds is displayed on the set value display.

- (9) An error is displayed if there is an error by the conformity check of setting data. Please check the contents of the error, because it is indicated by the text (8.1 section, 43~46 pages).
- (10) In error occurrence, the MEAS <u>SET</u> key is pushed again. Please check and correct the set value shown by the error code. Please perform from the above (8) after a correction end.
- (11) After setting finishing. Please setting changeover switch is OFF.

■ The setting operation method (A setting changeover switch is possible for setting at ON.)

 $\langle Caution \rangle$  The digit indicated by " $\Box$ " is blinking. MEAS/SET ITEM CODE MEAS · SET DATA **O** MEASURE ò **88** Ħ Ħ 88 MEAS/SET Item code 2 "O" **O** SET 0 Item code change  $[\Delta]$  key Voltage control ENTRY -MEAS/SET DISPLAY Item code 2 "1" pulse width Item code change  $[\Delta]$  key Closing allowable DISPLAY ENTRY MFAS/SFT Item code 2 "2" frequency difference Measure Set point updating  $\left[ \bigtriangleup \right]$  key Henceforth, a low-order digit is the code Control start and is rotation. 2"2"~2"9", 2"0" \_9ood\_ in new set point. A digit is shifted by the  $[\triangleright]$  key. Display (MEAS) SET)Key 🗲 A numerical value is changed by the  $|\Delta|$  key. Error Finally it decides by the ENTRY key. Item code change. It high-order digit-shifts message It control-continues by the by the [ > key. set value before set value change. CT ratio of generator ENTRY-MEAS/SET DISPLAY Item code "3" 0 three-phase input Item code change  $|\Delta|$  key Generator separation DISPLAY ENTRY MEAS/SET "4" 0 ltem code deviation possible Item code change  $[\Delta]$  key Henceforth, a high-order digit is the  $|\Delta|$  key A digit is shifted by the  $\triangleright$  key. "4"0~"7"0 "2"0 and is rotation. A numerical value is changed by the  $|\Delta|$  key. Finally it decides by the ENTRY key.

5.3 Caution on setting

- After setting is finished, please return to OFF by setting changeover switch.
- The planned control is unrealizable if there is a setting mistake. Please perform setting change carefully after checking set value.

key.

A low order digit shifts by the |D| key. And numerical selection at the  $[\Delta]$ 

- Before the update of setting data, if a setting changeover switch is OFF, the set value in change becomes invalid. Control is continued by the set value before setting change.
- Setting change cannot be performed from synchronous closing control.
- It is designed for the generator of more than 100kW of rated powers. Please consult with our company, if each rated (WRG, QRG, WFSI, WRI) setting is under 100kW (100kvar).

# 5.4 Setting item list

No.	Set	description	Mark	lnitial value	Possible range set	Synchronous control	Power receiving parallel Power distribution control + generator power-factor control	Generator individual Power distribution control + frequency, voltage control	Note
20		Closing allowable voltage difference	۵V	5%	1~10%	0	×	×	
21		Voltage control pulse width	VPW	0. 5s	0.1~1.0s	0	×	×	
22	Synchr-	Closing allowable frequency difference	∆F	0. 1Hz	0. 1, 0. 15, 0. 20, 0. 25, 0. 30Hz	0	×	×	It is the set value of synchronous
23	onous closing	Governor control pulse width	FPW	0. 5s	0.1~1.0s	0	×	×	It can set up at the
24	control	Voltage pulse output period	PI1	2s	1~5s	0	×	×	synchronizing start input OFF.
25		Circuit breaker progressive time	25	50ms	10~310ms ( <sup>6</sup> )	0	×	×	
26		Closing output continuation number of times	25N	1 time	O: No limiting 1: 1 time 2: 2 times 3: 3 times	0	×	×	
27	Receivin transduc	g power er full scale	WFSI	1200kW	100~99999kW	×	0	×	Set value of the transducer input sensitivity of power receiving. Only power receiving parallel needs to be set up.
28	Receivin measurem ( <sup>7</sup> )	g power ent average time	TAI	2s	0~120s	×	0	×	lt sets up if needed.
29	VT ratio 3-phase	of generator input	VT	60	1~9999	0	0	0	It is setting of VT
30	CT ratio 3-phase	of generator input	СТ	50	1~9999	×	0	0	generator.
31	Bus rate (VT seco	d voltage ndary)	۷	110V	90~120V	0	0	0	The rated voltage
32	Bus rate	d frequency	F	50. OHz	49.0∼51.0Hz 59.0∼61.0Hz	0	0	0	of rated frequency.
33	Power re power	ceiving maximum	WRI	600kW	100~WFSI	×	0	×	( <sup>10</sup> ) It is setting item
34 35	Generato	r starting power	WHI(1) WHI(2)	90%	20~95%	×	0	×	about receiving power constant
36 37	Power re control	ceiving constant power	WMI(1) WMI(2)	50%	10~87%	×	0	×	There is a limit of
38 39	Power re power	ceiving minimum	WLI(1) WLI(2)	20%	1~50%	×	0	×	≧WLI+∆WI other
40 41	Generato possible	r separation deviation	$\Delta M$ (1) $\Delta M$ (2)	10%	5~70%	×	0	×	and the range which
42 43	Receivin	g power dead band	$\Delta WI (2)$	10%	3~30%	×	0	×	Set value is % to WRI.
44	Power co pulse ti	ntrol maximum me	THW	3. Os	0. 5~5. Os	×	0	0	Control speed is
45	Power co pulse ti	ntrol minimum me ( <sup>8</sup> )	TLW	0. 3s	0.1~1.0s	×	0	0	set up.
46	Frequenc band	y control dead	∆FC	1.0%	0.2~5.0%	×	×	0	It is the setting item of frequency control at the case
47	Frequenc pulse ti	y control maximum me	THF	3. Os	0. 5~5. Os	×	×	0	of operation of only a generator.

						Power receiving	Generator	
No.	Set description	Mark	lnitial value	Possible range set	Synchronous control	Power distribution control + generator power-factor control	Power distribution control + frequency, voltage control	Note
48 49	Generator rated power (Generator maximum operation power)	WRG① WRG②	1500kW	100~(VT× CT)kW MAX. 9999kW	×	0	0	(11)
50 51	Next number machine starting power	WHG① WHG②	100%	70~100%	×	0	0	It is a setting item about next machine
52 53	Generator separation possible power	WMG① WMG②	80%	50~95%	×	0	0	starting power and separation
54	Generator minimum power	WLG	10%	1~40%	×	0	0	possible power. There is a limit of
55	Next machine starting deviation and separation possible deviation. (Only a generator is at the ream system case.)	Ш	20%	1~40%	×	×	0	WHG-5%≧WMG other than the following and the range which can be set up.
56 57	( <sup>9</sup> ) Generator power dead band	$\triangle$ WG(1) $\triangle$ WG(2)	2%	1~30%	×	0	0	WRG.
58	Reactive power control maximum pulse time	THQ	3. Os	0. 5~5. Os	×	0	0	Control speed is
59	Reactive power control minimum pulse time	TLQ	0. 3s	0.1~1.0s	×	0	0	set up.
60	Voltage control dead band	∆VC	2.0%	0.5~5.0%	×	×	0	Only generator is
61	Voltage control maximum pulse time	THV	3. Os	0. 5~5. Os	×	×	0	setting item of voltage control at operation.
62	Generator rated reactive power	QRG	750kvar	100~ (VT×CT)kvar MAX. 9999kvar	×	0	0	It is the set value of the rated reactive power of a generator.
63	Generator constant control power factor value	cosΦ	LAG90 %	LEAD (-) 95~100 ~LAG (+) 70%	×	0	×	
64	Power factor control dead band	$\triangle \Phi$	3°	2~10°	×	0	×	at the case of
65	Power factor control dead band change current value	CHA	30%	10~60%	×	0	×	control of a generator.
66	Power factor control cut current value	CTA	10%	1~10%	×	0	×	
67	Generator starting detection timer	TS	60s	0~120s	×	0	×	It is timer
68	Generator separation possible detection timer	TB	30s	0~60s	×	0	0	setting.
69	Governor control delay time	TGDL	2s	0~20s	×	0	0	
70	AVR control delay time	TADL	2s	0~20s	×	0	0	
71	Power receiving maximum pulse power deviation	∆WTHI	50%	50% fix value	-	-	-	
72	Generator all conduction pulse power deviation	∆WTRG	50%	10~70%	×	0	0	Control speed is
73	Generator maximum pulse power deviation	∆WTHG	30%	10~50%	×	0	0	set up.
74	Maximum pulse frequency deviation	∆FTH	10%	10% fix value	_	_	_	
75	Maximum pulse power factor deviation	$ riangle \Phi$ TH	60°	60° fix value	_	_	_	
76	Maximum pulse voltage deviation	$\triangle$ VTH	10%	10% fix value	_	-	_	

						Power receiving parallel	Generator individual	
No.	Set description	Mark	lnitial value	Possible range set	Synchronous control	Power distribution control + generator power-factor control	Power distribution control + frequency, voltage control	Note
77	Governor system abnormality detection	GAV	1	1:0N 2:0FF	0	0	0	It is existence or nonexistence setting of governor system abnormality detection.
78	Generator parallel operation number	Paral- lel number	1	1~8	0	0	0	It is setting of the operation quantity of generator.
79	Display turn off the light time	-	10 min.	0:Continuation 1~10 minutes	0	0	0	The 7 segment LED is turn off the light.

Note (<sup>6</sup>) <u>Relationship of possible progressive time 25 closing a</u>llowable frequency difference setting ( $\Delta F$ ) and set.

∆F set	Setting possible progressive time.
0.1 Hz	10~310ms
0. 15Hz	10~210ms
0.2 Hz	10~150ms
0. 25Hz	10~100ms
0.3 Hz	10~ 80ms

Note(<sup>7</sup>) Regardless of TAI (second), detection control of the power receiving reverse power detection is done by instantaneous value.

Note(<sup>8</sup>) The frequency control minimum pulse time is the power control minimum pulse time (TLW) and common use.

Note (9) They are a generator reactive power dead band and common use. However, it becomes % to QRG.

Note (<sup>10</sup>) Power receiving setting conditions. ① WFSI $\geq$ WRI ② WHI $-\Delta$ M $-\Delta$ WI $\geq$ WAI \geqWAI  $\geq$ WAI  $\geq$ WAI  $\geq$ WAI \geqWA

Note (11) Generator setting conditions. (1)  $VT \times CT \ge WRG$ 

6. Control function

6.1 Synchronous closing control

(1) Control range

Bus voltage	80~132V
Generator voltage	More than 80V
Bus frequency	Rated frequency $\pm 3$ Hz
Frequency difference $\Delta F$	Less than 4Hz

(2) Speed matcher function

The frequency difference of a bus and a closing generator controls the frequency of a closing generator to come in tolerance ( $\Delta F$  or  $\Delta F$ +0.1Hz).

About tolerance

·At the case of power receiving and parallel operation (power receiving start ON) :  $\Delta F$ 

• At the case of the parallel operation (power receiving start OFF) of only generator  $\Delta$ F+0.1Hz

- However, in case of  $\Delta F$ =0.3Hz setting. Tolerance is 0.3Hz.
  - in case of  $\Delta F$ =0.25Hz setting. Tolerance is 0.3Hz.

• Pulse output wave form

Control pulse width (FPW) : Constant pulse width (Setting to 0.1 $\sim$ 1.0s is possible.) Control pulse output cycle:1 / frequency difference (In phase difference 1 turn of 1 pulse output)



(3) Voltage balance function

The voltage difference of a bus and a closing generator controls the voltage of a closing generator to come in tolerance  $(\Delta V)$ .

Pulse output wave form Control pulse width (VPW) : Constant pulse width (Setting to 0.1~1.0s is possible.) Control pulse output cycle (PI1) : Constant pulse period (Setting to 1~5s is possible.)
Gontrol pulse width (VPW) 90R 90L Control pulse output period (PI1)
(4) Synchronous closing function ..... In case of ΔF. ΔV. In order to detect the phase point of agreement of a bus and a closing generator and to do the closed circuit of the circuit breaker by the synchronous point. The progressive time of a circuit breaker is forecasted and a closing command is outputted before a synchronous point.

A circuit breaker progressive time can be set as  $10 \sim 310$ ms.

- (5) Phase difference 15° within detection function  $\cdots$  In case of  $\Delta F$ ,  $\Delta V$ .
  - The phase difference of bus and closing generator is within 15°, a synchronous check relay signal is outputted. • Synchronous closing output



- Note(12) An alarm is outputted if a synchronous closing mistake occurs after 25N(1~3) of counts of closing output continuation. It is not outputted if unconditional in a closing output continuation count setting. Reset of an alarm output is performed by synchronous start input OFF.
- (6) Phase difference delay detection function

In order to speed up synchronous closing control in the next case, a governor control output is done after 3 seconds. (If the frequency difference (less than 0.05Hz) of a bus and a closing generator was small and the phase difference becomes constant)

25 closing command is not outputted from phase difference delay detection.

•65L is outputted at the case of SLOW closing designation.

• FAST or random closing designation outputs 65R.

#### 6.2 Power control

(1) Control conditions

Receiving power constant control: In parallel operation with power receiving. And at the case of ALS control designation. (Control start ON, Power receiving start ON, Distribution start ON, Function change switch: ALS or ALS+APFR) Power proportional distribution control: Only a generator is into operation. And at the case of ALS control designation. (Control start ON, Power receiving start OFF, Distribution start ON, Function change switch: ALS or ALS+APFR)

(2) Control range

Bus voltage:AC80~132V Bus frequency:Rated frequency F±7Hz

Receiving power constant control or power proportional distribution control is performed in control range. If a bus voltage input is other than the control range. : ERROR LED turn on the light and light trouble are outputted, and power control is stopped.

(3) Receiving power constant control. (At the case of parallel operation with power receiving.) In order that receiving power may serve as power receiving constant control value (WMI±ΔWI), proportional distribution control of the remaining power excluding the burden share (WMI) of power receiving from all power (receiving power + generator total power) is done between each generator. Thereby, receiving power is controlled by WMI constant.

# (Receiving power + Generator total power)

Each generator control object = <u>Power receiving constant control value WMI</u> ×100% (% for WRG) ×100%

The above calculation formula.

To the computed generator control object, in order that each generator may become in a generator control object  $\pm \Delta$ WG dead band, governor control is done. If the receiving power has not come in the power receiving constant control value (WMI $\pm \Delta$ WI) dead band (Even if all generators come in a generator control object  $\pm \Delta$ WG dead band), the minimum pulse is outputted in each generator. And, in order that receiving power may become in deltaWI dead band, it adjusts.

Example 1) Power receiving + 3 generators (WMI=100kW , WRG1 $\sim$ 3=500kW)



Example 2) Power receiving + 3 generators (WMI=100kW , WRG1 $\sim$ 2=500kW , WRG3=1000kW) If the rated powers of a generator are different





<Caution> It becomes a power proportional distribution control to a rated power WRG.

(4) Power proportional distribution control (at the case of isolated operation of generator only.) Proportional distribution control of all the power (generator total power) is done between each generator.

Each generator control object (% for WRG) =  $\frac{\text{Generator total power}}{\text{Summation of generator rated power WRG}} \times 100\%$ 

The above calculation formula.

To the computed generator control object, in order that each generator may become in a generator control object  $\pm \Delta$ WG dead band, governor control is done. All generators become in  $\Delta$ WG dead band, and a power proportional distribution control is completed. After that, bus voltage is supervised to all machine coincidence, and rated frequency control is performed.

Example) 3 generator (WRG1 $\sim$ 3=500kW)



Delay time is short.

(5) Governor pulse output waveform

65R output

A governor pulse output is controlled so that generator output becomes in generator control object  $\pm \Delta$ WG dead band. As for governor pulse output, pulse width changes with the deviation (control object - generator output of present) to control object.

In case of deviation is more than all conduction pulse power deviation ( $\Delta$ WTRG), it becomes a continuous pulse without governor control delay time (TGDL). And, in case of deviation is more than all conduction pulse power deviation ( $\Delta$ WTRG)  $\sim$  maximum pulse power deviation ( $\Delta$ WTRG), the pulse of the power maximum pulse time (THW) is outputted.

In case of deviation for maximum pulse power deviation ( $\Delta$ WTHG)  $\sim$  power dead band ( $\Delta$ WG), it is the pulse width at the case of power maximum pulse time (THW)  $\sim$  power minimum pulse time (TLW). The pulse of short pulse width is outputted as a control object is approached.



Governor delay time

(6) Setting of receiving power dead band In actual control, as for the control dead band, +1.0% of hysteresis is prepared in the outside of set value  $\Delta WI$ . Please set up dead band  $\Delta WI$  after taking this hysteresis into consideration.

The point that separates from a dead band and starts a governor pulse output again serves as a dead band set value  $\Delta WI + 1.0\%$  hysteresis.

(7) Setting of generator power dead band In actual control, as for the control dead band, +1.0% of hysteresis is prepared in the outside of set value  $\Delta$ WG. Please set up dead band  $\Delta$ WG after taking this hysteresis into consideration.

The point that separates from a dead band and starts a governor pulse output again serves as a dead band set value  $\Delta \text{WG}+1.0\%$  hysteresis.



- (8) Average value measurement control It is possible to perform distribution control of receiving power by average value by setting up receiving power measurement average time TAI second. CR filter processing with the time constant of the set-up value is performed by software.
- (9) Over load detection If generator power exceeds 110% of the rated power WRG, over load detection and a light trouble are outputted. However, control is continued.
- (10) Generator power maximum operation power The maximum operation power value of the generator at the case of power receiving and generator parallel operation is a rated power WRG. If this is exceeded, receiving power constant control is stopped. And, it becomes the generator maximum operation constant control of WRG±ΔWG.
- (11) Receiving power transducer input breaking detection If receiving power transducer input (receiving power average value) continues for 5 seconds in the status within OmA ±0.8mA, input breaking error detection and light trouble are outputted. And, control stops.
- (12) Power receiving reverse power prevention control In order to prevent the reverse power of power receiving, if receiving power (instantaneous value) constitutes below power receiving minimum power (WLI), distribution control is interrupted temporarily. And, if the status of power receiving reverse power (less than OkW) continues more than 10 seconds, power receiving reverse power error detection and a light trouble are outputted. However, power receiving reverse power control is continued.
  - (Caution) In order to prevent the motor ring of a generator, if generator power becomes below  $OkW + \Delta WG$ , the governor decrease maximum pulse is stopped. And, if it becomes below  $OkW + \Delta WG$  also in the usual control, a governor decrease signal is not outputted.
- (13) Governor system abnormality detection

If a generator does not reach an object even if it outputs a governor signal (65R, 65L) in the same direction 60 times continuation, a governor system abnormality detection and a light trouble are outputted. Governor system abnormality detection machine continues control. Other normal machines perform a quantity control and receiving power constant control except for an abnormal machine. And, effective/no effect setting is possible for governor system abnormality detection function by the setting item. Governor system abnormality detection is detected also in the case of all conduction pulse output.

<Caution> All conduction pulse output, "maximum pulse time + delay time" is counted as output for one pulse.

(14) Generator number control

Heavy burden OFF: Power receiving constant control priority mode. Heavy burden ON : Generator heavy burden operation priority mode.

Power receiving + Generator	Generator only
Start command output	<ul> <li>Start command output</li> </ul>
Common: As for starting of the first generator, power receiving load	(Heavy burden ON∕OFF common)
becomes more than WHI. It outputs, if it continues during TS sec.	If total load reaches more than "(WHG
Heavy burden OFF :	$-\Delta$ H) $ imes$ number of generator in
If total load reaches more than "WMI+WHG× number of generator	operation", a starting (with no timer)
in operation", a starting (with no timer) command will be	command will be outputted to the machine
outputted to the machine of the next order of operation.	of the next order of operation.
Heavy burden ON :	
If total load reaches more than "WHI+WHG× number of generator	<caution> According to power conditions.</caution>
in operation", if it continues TS second, a start command will	multiple start commands may be
be outputted to the machine of the next order of operation.	outputted simultaneously.
(Caution) According to power conditions, multiple start commands may be	
outputted simultaneously.	
Separation control	<ul> <li>Separation control</li> </ul>
Heavy burden OFF :	(Heavy burden ON∕OFF common)
The total load after the separation becomes below $"WMI+WMG imes$	The total load after the separation
generator number of remnant", if it continues TB sec the machine	becomes below "(WMG $-\Delta$ H) $ imes$ generator
of the last order of operation will start separation control.	number of remnant", if it continues TB
Heavy burden ON :	sec the machine of the last order of
The total load after the separation becomes below "(WHI – $\Delta$ M)	operation will start separation
+WHG× generator number of remnant", if it continues TB sec the	control.
machine of the last order of operation will start separation	
control.	
Common: The separation of the last generator starts separation control.	
if total load becomes below WHI $-\Delta M$ and continues TB sec.	
Common: The separation of the last generator starts separation control, if total load becomes below WHI $-\Delta M$ and continues TB sec.	

Operation at the case of communication malfunction detection

Starting output
 The start command output by the offering start is possible. Moreover, in power receiving parallel, a start command is outputted on the starting conditions of the first generator of power receiving + generator. (Power receiving load ≥ WHI, TS sec continuation)
 Separation control : In power receiving parallel, the separation control by the forced separation is possible. Moreover, separation control is performed on the separation conditions of the last generator of power receiving + generator. (Power receiving load + self-machine load ≤ WHI-ΔM, TB second

continuation)

#### (15) Separation of generator

If the generator in separation control reaches separation power (WLG+ $\Delta$ WG), separation command will be outputted. If it is status as continued, constant control of separation power (WLG)  $\pm \Delta$ WG is performed.

(16) Offering start

Regardless of the loaded condition and starting order of generator, start command is outputted by the Offering start input. Separation control of all generators is stopped from a starting output (until distribution start is inputted). If the offering start input is applied to the generator in parallel operation, the generator separates from the object of automatic separation control. (The order of separation can be flown)

If closing of large capacity load is forecasted, generator can be held before application of load by applying a offering start input to all the generators of the required number with low loaded condition.

(17) Forced separation

It is possible to do the separation of the generators arbitrary irrespective of separation command by the forced separation input, and if there is a standby generator, after starting a standby generator, separation control is started. If there is no standby generator, separation control is started only at the case of power receiving and parallel. It is effective in the case of failure of a generator or check. If the forced separation input is applied to the generator in stop, it is excepted from the object of automatic starting. And, although a few set input is possible for a forced separation, it performs one separation control every.

Other forced separation standby machines do not output governor increase (65R) signal. The timer for about 10 seconds is contained until it starts forced separation.

(18) Lead generator designation

The order of operation of a generator is determined. Please designate one set from the generator in a system (that to which the control start input is applied). (If not designated, an error is detected and a light trouble output is done)

From the generator which had the advantage generator designated, it starts in order of the address.

The separation is done to an address inverse order from the generator put into operation at the end.

An advantage generator can be designated arbitrarily. An operation machine is changed if an advantage generator is changed from operation (it becomes the designated order of operation).

(Example)	The order	of operation.	(Example)	The
	A 1 1 .			

Advantage machine designation 

order of separation. Advantage machine designation

_>1→2	• 3→	4→5→	6→7→	8 —			1←2	• 3←4•	-5←6←	-7←8 <	

<Caution> The machine of the control start OFF or the machine more than operation quantity flies and controls. If a lead generator designation machine has a generator in load distribution (offering start machine is excluded.) in others, it will output a start command regardless of power conditions.

(19) Control change

It is at a control change input and it is possible to change the power control value of power receiving and a generator from ① to ②. It is combination with a control changeover switch, and switching of the following (No. ① to ④) pattern is possible. It is effective in the change control by the daytime/night, summer / winter, weekday / holiday, etc.

	Control obongo	Control cha	nge switch.	Power cont	rol value	
No.	input	Power receiving mode	Generator mode.	Power receiving	Generator	Description
1	ON OFF	MODE 1	MODE 1	WHI WMI WLI AM	$ \left. \begin{array}{c} WRG \\ WHG \\ WMG \\ \Delta WG \end{array} \right\} $ (1)	With no switching of a power control value.
	OFF	NODE 1	MODE 2	$ \begin{array}{c} WHI \\ WMI \\ WLI \\ \Delta M \\ \Delta WI \end{array} $	WRG WHG WMG △WG	With no switching of a power control value.
2	ON	MODE 1		$ \left. \begin{array}{c} WHI \\ WMI \\ WLI \\ \Delta M \\ \Delta WI \end{array} \right\} \textcircled{1}$	$ \left. \begin{array}{c} \text{WRG} \\ \text{WHG} \\ \text{WMG} \\ \Delta \text{WG} \end{array} \right\} \textcircled{2}$	Only the power control value of a generator is changed to ①→②.
3	0FF	MODE 2	MODE 1	$ \left. \begin{array}{c} WH I \\ WM I \\ WL I \\ \DeltaM \\ \DeltaW I \end{array} \right\} \textcircled{1} $	$ \left. \begin{array}{c} \text{WRG} \\ \text{WHG} \\ \text{WMG} \\ \Delta \text{WG} \end{array} \right\} \textcircled{1}$	With no switching of a power control value.
3	ON			MODE 1	WHI WMI WLI $\Delta M$ $\Delta W$	$ \left. \begin{array}{c} \text{WRG} \\ \text{WHG} \\ \text{WMG} \\ \Delta \text{WG} \end{array} \right\} \textcircled{1}$
4	0FF	MODE 2	MODE 2 MODE 2	WHI WMI WLI $\Delta M$ $\Delta W$	$ \left. \begin{array}{c} WRG \\ WHG \\ WMG \\ \Delta WG \end{array} \right\} \textcircled{1}$	With no switching of a power control value.
	ON			WHI WMI WLI AM AWI	WRG WHG WMG △WG	The power control value of both power receiving and generator is changed to $\mathbb{T} \rightarrow \mathbb{Q}$ .

#### 6.3 Rated frequency control

(1) Rated frequency control

In operation of only a generator, all generators become in  $\Delta$ WG dead band. All machines supervise bus voltage simultaneously after completing a power proportional distribution control. And, rated frequency control is performed.

(2) Governor pulse output waveform

In each generator, in order that it may become bus rated frequency  $F \pm \Delta FC$  to which generator frequency was set, governor control is done. As for a governor pulse output, pulse width changes with the deviation (control object - generator output of present) to a control object. Deviation is at the case more than the maximum pulse deviation ( $\Delta FTH$ ), the pulse of the maximum pulse time THF is outputted. Deviation (between  $\Delta FTH \sim \Delta FC$ ) outputs the pulse of short pulse width as it approaches a control object by the pulse width between THF ~TLW.



(a) Governor pulse width in frequency control.

The deviation and the following set value to a control object determine pulse width.

- Item No. 47 Frequency control maximum pulse time (THF)
- Item No.45 Power control minimum pulse time (TLW)
- Item No. 46 Frequency control dead band ( $\Delta$ FC)

Item No. 74 Maximum pulse frequency deviation ( $\Delta$ FTH)

Pulse width = 
$$TLW + \frac{(THF - TLW)}{(\Delta FTH - \Delta FC)} \times (Deviation to control object - \Delta FC)$$
 (s)

(b) Governor control delay time

Please set up setting of governor control delay time in consideration of the response time of the external device containing a governor device etc. To the response time, if setting of delay time is short, it becomes the cause of overshoot or undershoot of a generator output.

(3) Setting of frequency dead band
 In actual control, as for the control dead band, +0.1%
 of hysteresis is prepared in the outside of set value
 ΔFC.
 Please set up dead band ΔFC after taking this

hysteresis into consideration.

The point which separates from a dead band and starts a governor pulse output again constitutes a dead band set value  $\Delta FC+0.1\%$  hysteresis.



(4) Governor system abnormality detection

If a generator does not reach an object even if it outputs a governor signal (65R, 65L) in the same direction 60 continuation, it detects the abnormality of governor system. And, a light trouble is outputted. Governor system abnormality detection machine continues control. However, other normal machines perform rated frequency control except for an abnormal machine. And, effective/no effect setting is possible for governor system abnormality detection by the setting item.

- 6.4 Generator power factor constant control (Parallel operation of power receiving and a generator)(1) Control conditions
  - It APFR control designates in parallel operation with power receiving. (Control start ON, Power receiving start ON, Distribution start ON, Function switching: APFR or ALS+APFR)
  - (2) Control range

Bus voltage :80~132V Bus frequency:Rated frequency F±7Hz

Generator power-factor constant control is performed to above control range. At the case outside the control range of bus voltage input, ERROR LED is turn on the light. And, a light trouble is outputted. Furthermore, generator power-factor constant control is stopped.

(3) Generator power-factor constant control

In each generator, in order that it may become the modulus value of generator constant controlling force  $\cos \Phi \pm \Delta$   $\Phi$  to which the generator power-factor was set. AVR control is performed.

(4) AVR pulse output waveform

As for an AVR pulse output, pulse width changes with the deviation (control object - generator output of present) to a control object. Deviation is at the case more than the maximum pulse deviation ( $\Delta$ TH), the pulse of the maximum pulse time THQ is outputted. Deviation (between  $\Delta \phi$ TH $\sim \Delta \phi$ ) outputs the pulse of short pulse width as it approaches a control object by the pulse width between THQ $\sim$ TLQ.



(a) AVR pulse width in power-factor control

The deviation and the following set value to a control object determine pulse width.

Item No. 58 Reactive power control maximum pulse time (THQ)

- Item No. 59 Reactive power control minimum pulse time (TLQ)
- Item No. 64 Power-factor control dead band ( $\Delta \phi$ )
- Item No. 75 Maximum pulse power-factor deviation ( $\Delta \phi$ TH)

Pulse width = TLQ+
$$\frac{(THQ-TLQ)}{(\Delta \phi TH - \Delta \phi)}$$
 × (Deviation to control object -  $\Delta \phi$ ) (s)

(b) AVR control delay time

Please set up setting of AVR control delay time in consideration of the response time of the external device containing an AVR device etc. To the response time, if setting of delay time is short, it becomes the cause of overshoot or undershoot of generator output. (5) Setting of power-factor dead band AVR output AVR output In actual control, as for the control dead band. +1.0° of hysteresis is prepared in the outside of set value  $\Delta \Phi$ . +1.0° hysteresis Please set up dead band  $\Delta \phi$  after taking this Generator constant ΔΦ hysteresis into consideration. control powerfactor value The point which separates from a dead band and ΔΦ COS Ø starts a AVR pulse output again constitutes a dead band set value  $\Delta \phi + 1.0^{\circ}$  hysteresis. +1.0° hysteresis AVR output AVR output

(6) Power-factor dead band change current value Power-factor dead band change current value (CHA)  $\leq$  Load current: A power-factor dead band is  $\Delta \phi$ . Power-factor dead band change current value (CHA) > Load current: A power-factor dead band is  $\Delta \phi \times 2$ . As mentioned above, generator power-factor constant control is performed.

- (7) Power-factor control cut current value Power-factor control cut current value (CTA) > Load current : Generator power-factor constant control is stopped.
- (8) Over load detection An over load is detected if generator reactive power exceeds LAG110% or LEAD55% of the rated reactive power QRG. And, a light trouble is outputted. However, control is continued.
- (9) Generator reactive power maximum operation limiter control If the reactive power maximum operation value (more than the LAG side limiter value QRG, and more than the LEAD side limiter value QRG/2) of a generator is exceeded, generator power-factor constant control is stopped. And, it becomes the maximum operation limiter control.
- (10) AVR system abnormality detection If a generator does not reach an object even if it outputs an AVR signal (90R, 90L) in the same direction 60 continuation, it detects the abnormality of AVR system. And, a light trouble is outputted. However, generator power-factor constant control is continued.
- 6.5. Reactive power proportional distribution control (Parallel operation of only a generator)
  (1) Control conditions
  When only a generator designates APFR control from operation.
  (Control start ON, Power receiving start OFF, Distribution start ON, Function switching: APFR or ALS+APFR)
  - (2) Control range
     Bus voltage :80~132V
     Bus frequency: Rated frequency F±7Hz
     Reactive power proportional distribution control is performed to above control range.
     At the case outside the control range of bus voltage input, ERROR LED is turn on the light. And, a light trouble is
     outputted. Furthermore, reactive power proportional distribution control is stopped.
  - (3) Reactive power proportional distribution control Proportional distribution control of all the reactive power is done between each generator.

Each generator control object =  $\frac{\text{Generator total reactive power}}{\text{The summation of the generator rated reactive power QRG}} \times 100\%$ 

To the generator control object computed from the upper type, in order that each generator may constitute generator control object  $\pm \Delta WG$  (inside of  $\Delta QG$  dead band), AVR control is done. All generators become in  $\Delta QG$  dead band, after completing reactive power proportional distribution control, bus voltage is supervised to all machine coincidence, and rated voltage control is performed to them.

(4) AVR pulse output waveform

AVR pulse output is controlled so that generator output constitutes generator control object  $\pm \Delta WG$  (inside of  $\Delta QG$  dead band). As for an AVR pulse output, pulse width changes with the deviation (control object - generator output of present) to control object. When deviation is more than the maximum pulse deviation ( $\Delta WTHG$ ), the pulse of the maximum pulse time THQ is outputted. Deviation (between  $\Delta WTHG \sim \Delta WG$ ) outputs the pulse of short pulse width as it approaches a control object by the pulse width between THQ $\sim$ TLQ.



- (a) AVR pulse width in reactive power control The deviation and the following set value to a control object determine pulse width. Item No. 58 Reactive power control maximum pulse time (THQ) Item No. 59 Reactive power control minimum pulse time (TLQ) Item No. 56, 57 Generator power dead band ( $\Delta$ WG)

  - Item No. 73 Generator maximum pulse power deviation ( $\Delta$ WTHG)

Pulse width =  $TLQ + \frac{(THQ - TLQ)}{(\Delta WTHG - \Delta WG)} \times (Deviation to control object - \Delta WG)$  (s)

(b) AVR control delay time

Please set up setting of AVR control delay time in consideration of the response time of the external device containing an AVR device etc. To the response time, if setting of delay time is short, it becomes the cause of overshoot or undershoot of generator output.

(5) Setting of dead band

In actual control, as for the control dead band, +1.0% of hysteresis is prepared in the outside of set value  $\Delta$ WG. Please set up dead band  $\Delta$ WG after taking this hysteresis into consideration.

The point which separates from a dead band and starts a AVR pulse output again constitutes a dead band set value  $\Delta \text{WG}+1.0\%$  hysteresis.



(6) Over load detection

An over load is detected if generator reactive power exceeds LAG110% or LEAD55% of the rated reactive power QRG. And, a light trouble is outputted. However, control is continued.

(7) AVR system abnormality detection

If a generator does not reach an object even if it outputs an AVR signal (90R, 90L) in the same direction 60 continuation, it detects the abnormality of AVR system. And, a light trouble is outputted.

AVR system abnormality detection machine continues control. However, other normal machines perform reactive power proportional distribution control except for an abnormal machine.

## 6.6 Rated voltage control

#### (1) Rated voltage control

In operation of only a generator, all generators become in  $\Delta QG$  dead band. All machines supervise bus voltage simultaneously after completing a reactive power proportional distribution control. And, rated voltage control is performed.

(2) AVR pulse output waveform

In each generator, in order that it may be set to bus rated voltage  $V\pm\Delta VC$  to which generator voltage was set. AVR control is done. As for a AVR pulse output, pulse width changes with the deviation (control object - generator output of present) to a control object. Deviation is at the case more than the maximum pulse deviation ( $\Delta VTH$ ), the pulse of the maximum pulse time THV is outputted. Deviation (between  $\Delta VTH \sim \Delta VC$ ) outputs the pulse of short pulse width as it approaches a control object by the pulse width between THV $\sim$ TLQ.



(a) AVR pulse width in voltage control.

The deviation and the following set value to a control object determine pulse width.

- Item No. 61 Voltage control maximum pulse time (THV)
- Item No. 59 Reactive power control minimum pulse time (TLQ)
- Item No. 60 Voltage control dead band ( $\Delta$ VC)
- Item No. 76 Maximum pulse voltage deviation ( $\Delta$ VTH)

Pulse width = 
$$TLQ + \frac{(THV - TLQ)}{(\Delta VTH - \Delta VC)} \times (Deviation to control object - \Delta VC)$$
 (s)

(b) AVR control delay time

Please set up setting of AVR control delay time in consideration of the response time of the external device containing an AVR device etc. To the response time, if setting of delay time is short, it becomes the cause of overshoot or undershoot of generator output.

(3) Setting of voltage dead band

In actual control, as for the control dead band, +1.0% of hysteresis is prepared in the outside of set value  $\Delta$ VC. Please set up dead band  $\Delta$ VC after taking this

hysteresis into consideration.

The point which separates from a dead band and starts a AVR pulse output again constitutes a dead band set value  $\Delta$ VC+1.0% hysteresis.



(4) AVR system abnormality detection

If a generator does not reach an object even if it outputs an AVR signal (90R, 90L) in the same direction 60 continuation, it detects the abnormality of AVR system. And, a light trouble is outputted. AVR system abnormality detection machine continues control. However, other normal machines perform rated voltage

AVR system abnormality detection machine continues control. However, other normal machines perform rated voltage control except for an abnormal machine.

- 7. Operation outline
- 7.1 Before control start
  - ① The controller contained in an operation quantity applies a power supply constantly. In order to perform communications processing, if it does not contain the number of control (if a control start is OFF by check or repair of generator etc.), should also apply a power supply.

<Caution> A communication error is displayed if a power supply apply is not done. Control is continued except for an error machine.

② The address determines the operation order of a generator, and the order of communication between controllers.

The address is set up in order that there may be no empty number to 1  $\sim$  operation quantity.

If an empty number occurs, an empty number is designated as a communication error machine. And, control is performed in the number few one set.

If the address overlaps and is set up, it is designated as a communication data error machine.

Control is continued except for an error machine.

③ Change of set value

Address modification in operation is not received. Address modification is performed with the auxiliary power supply OFF. Change of an operation quantity is performed immediately. If it changes simultaneously with the address, address modification is performed previously. All machine invocations of the change of an operation quantity are done at each generator each. A setting change is not made from synchronous closing control.

7.2 Synchronous closing control

- ① The voltage and frequency of a generator are established. After that, a synchronous control start is done in a synchronizing start input.
- O It controls in voltage  $\pm \Delta V$  and frequency  $\pm \Delta F$ . After that, 25 closing commands are outputted before a progressive time from a synchronous point. Contact ON time is made into of progressive times +200ms.
- ③ Detection of a synchronous closing mistake. In spite of having outputted 25 closing commands, after the case (synchronous closing mistake) where a synchronous point is passed occurs by the count of closing output continuation, it detects after phase difference 10° + about 1 sec efflux, and alarm is outputted. If unconditional setting of the count of closing output continuation is done, an alarm will not be outputted but will repeat a synchronous closing. Reset of an alarm is performed by OFF of a synchronizing start signal.
- The synchronous control re-start of closing mistake detection ③. It sets to ON again after the synchronizing start OFF.
- ⑤ The generator in parallel operation is control as follows, if the generator which started synchronous control in the system is detected.
  - At the case of parallel operation with power receiving
  - ···· Governor control and AVR control are continued.
  - At the case of generator individual operation.
  - ···· Governor control and AVR control are interrupted temporarily (2 minutes). Control is resumed after that.
- $^{\odot}$  If more than two synchronizing starts are inputted simultaneously,  $\Delta F$  and  $\Delta V$  control is performed simultaneously. And, a closing order is as follows.
  - At the case of parallel operation with power receiving
  - ···· It supplies from the generator included in closing conditions. More than one may be supplied simultaneously. At the case of generator individual operation.
    - ···· For 2 minutes after a synchronizing start input, it supplies according to the order of operation.
      - It supplies from the generator included in closing conditions after 2-minute efflux.
- $\bigcirc$  A synchronizing start sets to OFF after closing finishing.
- If the setting switch constitutes ON, a synchronizing start becomes no effect and synchronous control is not started. And, setting change in synchronous control cannot be performed, either.
- Synchronous control at the case of power failure recovery. The distribution control between all generators is stop (Distribution start OFF). Please perform a bus input change externally. After that, it is made the synchronizing start ON. In order to perform stable control, please form the timer for 0.5 seconds or more between the distribution start OFF (+ bus input switching) and the synchronizing start ON.

7.3 Distribution control

Power distribution control, rated frequency control, generator power-factor control, and rated voltage control are selected by each start input.

(1) Power distribution (at the case of switch ON of distribution start input and ALS or ALS+APFR)

Power receiving + Generator	<ul> <li>① Power receiving constant value = WMI</li> <li>② Reverse power of power receiving. Generator over load check.</li> <li>③ Power distribution (Proportional distribution)         Each generator burden = Total load - Power receiving constant value         Generator receiving constant value     </li> </ul>
Generator only	<ul> <li>① Over load check of generator</li> <li>② Power distribution (Proportional distribution)</li> <li>Each generator burden = Generator rated summation     </li> </ul>

(2) Rated frequency constant (at the case of switch ON of distribution start input and ALS or ALS+APFR)

Power receiving + Generator	
Generator only	After power distribution end, rated frequency control is performed to all machine coincidence.

(3) Power-factor constant (at the case of switch ON of distribution start input and APFR or ALS+APFR)

Power receiving + Generator	$\bigcirc$ Generator power-factor constant value = $\cos \phi$					
	② Generator reactive power over load check.					
	③ Generator power-factor is control to constant value.					
Generator only	${f ar O}$ Reactive power over load check of generator					
	$\oslash$ Reactive power distribution (Proportional distribution)					
	Feeb generator reactive power burden - Total reactive power					
	Generator rated reactive power summation					

(4) Rated voltage constant (at the case of switch ON of distribution start input and APFR or ALS+APFR)

Power receiving + Generator	
Generator only	After reactive power distribution end, rated voltage control is performed to all machine coincidence.

7.4 Control example of operation quantity (In case of 5 generator parallel)
 Starting and distribution control. (Power receiving constant control mode)

Operation quantity	Load distribution state	Control value
		① When load power increases and only power receiving amounts
	WMG	to 540kW in operation, a generator start command is
	(1200kW)	outputted after TS second.
(1)		
Power receiving	WHI	
only	(540kW) 🔶	
01113	(300kw)	Cancel is 420kW ( <u>WHI+WMI</u> )
	(300KW)	
	WI G1 G2 G3 G4 G5	
(2)	WHG	② The load assignment after linkage of nower receiving and
Power receiving and	(1500kW)	one generator
one generator		Pacaiving newer : WWI (2001/W) Constant control
		Concreter No. 1 newer: Remaining newer (240kW)
	WH I (540kW)	
	WM1 240kW	
	(300kW)	
(1)	WI 61 62 63 64 65	
(3)	WHG (1500kW)	③ Total load increases by linkage operation of power
Power receiving and	WMG	receiving and one generator.
one generator.	(1200kW)	If WMI(300kW) + WHG(1500kW) = 1800kW is exceeded,
		A next number machine start command outputs.
	(WH1	
	(540kW)	
	(300kW)	Concol is 16EOKW (WWILL WHG+WMG)
	WI G1 G2 G3 G4 G5	
	WHG (1EOOLw)	④ The load assignment after linkage of power receiving and
	(1500KW) WMG	two generators.
		Receiving power : WMI (300kW) Constant control
(4)	_ 750kW	Generator No. 1 power: 750kW
Power receiving and	WHI WHI	Generator No. 2 power: 750kW proportional distribution
two generators.	(540kW)	
	(000KW)	
	WI G1 G2 G3 G4 G5	
(5)	WHG	© Total load increases by linkage operation of power
Power receiving and	(1500kW)	receiving and two generators
two generators	WMG (1200kW)	If WMI (300kW) + WHG (1500kW) $\times 2$ (set) = 3300kW is exceeded
		A next number machine start command outputs
		A HOAT HUMBOT MUCHTIC STALL COMMAIN OUTPUTS.
	(540kW)	
	(WM1 m	
	(300kW)	Cancel is 3000kW   WMI+ ×2
(6)	mi 01 02 03 04 03   ⊎⊔∩	A The load appignment often Linkage of newsy years wing and
(O) Rowor receiving and		three generators
Fower receiving and		LIIFEE BEHERALUES.
Luree generators.		Receiving power . WMI(300KW) Constant control
		Generator No. I power · TUUUKW
	(540kw)	Generator No. 2 power: IUUUKW
	WMI	Generator No. 3 power : IUUUKW proportional distribution
	(300kW)	
	WLG	
	WI 61 62 63 64 65	
(/)	WHG (1500kW)	⑦ Iotal load increases by linkage operation of power
Power receiving and	WMG	receiving and three generators.
three generators.	(1200kW)	It WMI (300kW) + WHG (1500kW) $\times$ 3 (set) = 4800kW is exceeded,
		A next number machine start command outputs.
	(FAOLW)	
	(300kW)	Cancel is $4350 \text{kW}$   WWI + $\frac{\text{WHG} + \text{WMG}}{\text{W} \times 3}$
	wLG	
	WI G1 G2 G3 G4 G5	

Operation quantity	Load distribution state	Control value
(8)	WHG	The load assignment after linkage of power receiving and
Power receiving and	/1125kW (1500kW)	four generators.
four generators.	(1200kW)	Receiving power : WMI(300kW) Constant control
		Generator No.1 power:1125kW
	WHI WHI	Generator No.2 power:1125kW
	(540kw)	Generator No.3 power: 1125kW
	(300kw)	Generator No.4 power: 1125kW proportional distribution
	WI G1 G2 G3 G4 G5	
(9)	WHG (1500kW)	O Total load increases by linkage operation of power
Power receiving and	WMG	receiving and four generators.
four generators.	(1200kW)	If WMI (300kW) + WHG (1500kW) $\times$ 4 (set) = 6300kW is exceeded,
		A next number machine start command outputs.
	(F40(w)	
	(340KW) WM1	
	(300kW)	Cancel is 5700kW WMI + $\frac{WHG + WMG}{2} \times 4$
	WLG	
(10)	WI 61 62 63 64 65	The load appigment offer linkage of newer receiving and
(10) Dowor receiving and		five generators
five generators	WMG (1200kW)	Receiving nower : WWI (300kW) Constant control
		Generator No 1 nower: 1200kW
		Generator No.2 power: 1200kW
	(540kW)	Generator No.3 power: 1200kW
	(300kw)	Generator No. 4 nower: 1200kW
	(300km)	Generator No.5 power: 1200kW proportional distribution
	WI G1 G2 G3 G4 G5	
(11)	WHG (1500/w)	① Total load increases by linkage operation of power
Power receiving and	WMG	receiving and five generators.
five generators.	(1200kW)	If WMI(300kW) + WHG(1500kW) $\times$ 5(set) = 7800kW is exceeded.
		A generator does WRG constant control. Power receiving
	WHI	shares the remaining load.
	(540kW)	
	(300kW) <sup>-</sup>	<code><caution></caution></code> The above is the case where it is set as WRG=WHG.
	WLG	In case of WRG>WHG, it becomes WRG constant
	WI G1 G2 G3 G4 G5	control.

• Separation and distribution control (Power receiving constant control mode)

Operation quantity	Load distribution state	Control value
(12) Power receiving and five generators.	WHG (1500kW) (1200kW) (1200kW)	<ul> <li>Total load decreases by linkage operation of power receiving and five generators.</li> <li>If below WMI (300kW) + WMG (1200kW) × 4 (set) = 5100kW.</li> <li>An operation order is the last generator (with generator in operation), separation control is started after TB second.</li> </ul>
	(300kW) WI G1 G2 G3 G4 G5	Cancel is 5700kW $\left( WMI + \frac{WHG + WMG}{2} \times 4 \right)$
(13) Power receiving and four generators.	WHG (1500kW) (1200kW (1200kW)	<ul> <li>The load assignment after one generator separation. Receiving power : WMI (300kW) Constant control Generator No. 1 power : 1200kW Generator No. 2 power : 1200kW Generator No. 3 power : 1200kW Generator No. 4 power : 1200kW proportional distribution</li> </ul>
(14) Power receiving and four generators.	WHG (1500kW) WMG (1200kW) WMI (300kW) WI G1 G2 G3 G4 G5 WI G1 G2 G3 G4 G5	Total load decreases by linkage operation of power receiving and four generators. If below WMI (300kW) + WMG (1200kW) × 3 (set) = 3900kW. An operation order is the last generator (with generator in operation), separation control is started after TB second. Cancel is 4350kW (WMI + WHG + WMG 2 × 3)

Operation quantity	Load distribution state	Control value
(15) Power receiving and three generators.	WH I         (1500kW)           (1540kW)         WMG           (1200kW)         WLG	<ul> <li>The load assignment after one generator separation. Receiving power : WMI (300kW) Constant control Generator No. 1 power : 1200kW Generator No. 2 power : 1200kW Generator No. 3 power : 1200kW proportional distribution</li> </ul>
(16) Power receiving and three generators.	WH 01 62 63 64 65 (1500kW) (1200kW) (1200kW) (300kW) WM 0 (1200kW) WH 0 (1200kW) WH 0 (1200kW) WH 0 (1200kW) WH 0 (1200kW) WH 0 (1200kW) WH 0 (1200kW) WH 0 (1200kW) WH 0 (1200kW)	Total load decreases by linkage operation of power receiving and three generators. If below WMI (300kW) + WMG (1200kW) × 2 (set) = 2700kW. An operation order is the last generator (with generator in operation), separation control is started after TB second. Cancel is 3000kW (WMI + WHG+WMG/2 × 2)
(17) Power receiving and two generators.	WH G1 G2 G3 G4 G5 WHG (1500kW) WMG (1200kW) WMG (1200kW) WMG WMI (300kW) WI G1 G2 G3 G4 G5 WHG WHG WHG WHG (1200kW) (1200kW) (120	<ul> <li>The load assignment after one generator separation. Receiving power : WMI (300kW) Constant control Generator No. 1 power : 1200kW Generator No. 2 power : 1200kW proportional distribution</li> </ul>
(18) Power receiving and two generators.	WHG (1500kW) WMG (1200kW) (300kW) (300kW) WLG	Total load decreases by linkage operation of power receiving and two generators. If below WMI (300kW) + WMG (1200kW) × 1 (set) = 1500kW. An operation order is the last generator (with generator in operation), separation control is started after TB second. Cancel is 1650kW (WMI + WHG+WMG/2 × 1)
(19) Power receiving and one generator.	WH G1 G2 G3 G4 G5 WHG (1500kW) WMG (1200kW) WLG (1200kW) WLG (1200kW) WLG (1200kW) WLG (1200kW) WLG (1200kW) WLG (1200kW) WLG (1200kW) WLG (1200kW) WLG (1200kW) WLG (1200kW) WLG (1200kW) WLG (1200kW) WLG (1200kW) WLG (1200kW) WLG (1200kW) WLG (1200kW) WLG (1200kW) WLG (1200kW) WLG (1200kW) (1	<ul> <li>The load assignment after one generator separation. Receiving power : WMI (300kW) Constant control Generator No. 1 power: 1200kW proportional distribution</li> </ul>
(20) Power receiving and one generator.	WH I	Total load decreases by linkage operation of power receiving and one generator. If below WHI (540kW) $-\Delta M$ (60kW) = 480kW. Separation control of the last generator is started after TB second.Cancel is 510kW (WHI - $\frac{\Delta M}{2}$ )
(21) Power receiving only	WH G1 G2 G3 G4 G5 WHG (1500kW) WWG (1200kW) WWG (1200kW) WUG (1200kW) WUG (1200kW) WUG (1200kW) WUG (1200kW)	② Load after a generator separation. Receiving power∶480k₩

• Starting and distribution control (Generator heavy burden operation mode)

Operation quantity	Load distribution state	Control value
	WHG (1EOOLW)	① When load power increases and only power receiving amounts
	(1300KW)	to 540kW in operation, a generator start command is
		outputted after TS second
(1)		
(1)		
Power receiving	WHI	
only	(540kW)	
-	(200/w)	Cancel is 420kW WHI+WMI
	WI GI GZ G3 G4 G5	
(2)		② The load assignment after linkage of power receiving and
Power receiving and		one generator.
one generator		Receiving power : WMI (300kW) Constant control
		Consister No. 1 newer: Remaining newer (240kW)
		Generator No. I power - Remaining power (240kw)
	WH I	
	(340kW)	
	(300kW)	
	WI G1 G2 G3 G4 G5	
(2)		Tatal land increases by Linkage encretion of newer
(3)	(1500kW)	S Total load increases by linkage operation of power
Power receiving and	WMG	receiving and one generator.
one generator.	(1200kW)	If WHI (540kW) + WHG (1500kW) = $2040$ kW is exceeded,
		A next number machine start command outputs after TS
	w	second
	(540kW)	3000110.
	WM1 1 1 1	
	(300kW)	(WHI + WMI)
	WLG	Cancel is 1920kW
	WI G1 G2 G3 G4 G5	
(4)	WHG	④ The load assignment after linkage of nower receiving and
Power receiving and	(1500kW)	two generators
two generators.	870kW (1200kW)	Receiving power : WMI(300kW) Constant control
		Generator No.1 power:870kW
	WHI	Generator No.2 power: 870kW proportional distribution
	(540kW)	
	(2001/w)	
	(300kw)	
(5)	(1500kW)	(5) lotal load increases by linkage operation of power
Power receiving and	WMG	receiving and two generators.
two generators.	(1200kW)	If WHI (540kW) + WHG (1500kW) $\times$ 2 (set) = 3540kW is exceeded,
-		A next number machine start command outputs after TS
		second
	(540kW)	Subund.
	(300kW)	
	WLG	Cancel is 3420kW
	WI G1 G2 G3 G4 G5	
(6)	WHG	6 The load assignment after linkage of nower receiving and
Dowor receiving and	(1500kW)	three generators
Power receiving and		
three generators.	¥ (1200KW)	Receiving power : WMI(300kW) Constant control
		Generator No.1 power:1080kW
	WHI WHI	Generator No.2 power:1080kW
	(540kW)	Generator No.3 power: 1080kW proportional distribution
	או טו טע טע טע גע איז א א גע	
(7)	WHG (1500kW)	⑦ Iotal load increases by linkage operation of power
Power receiving and	WMG	receiving and three generators.
three generators.	(1200kW)	If WHI (540kW) + WHG (1500kW) $\times$ 3 (set) = 5040kW is exceeded.
		A next number machine start command outputs after TS
		sacond
	(540kW)	Second.
	WMI 1	
	(300kW)	( WHI + WMI )
	WLG	Cancel is 4920kW  +WHG×3
	'WI 'G1 'G2 'G3 'G4 'G5 '	

Operation quantity	Load distribution state	Control value
(8)		(8) The load assignment after linkage of power receiving and
Power receiving and	1185kW (1500kW)	four generators.
four generators.	(1200kW)	Receiving power : WMI(300kW) Constant control
		Generator No.1 power:1185kW
	WHI I I I I I I	Generator No.2 power:1185kW
	(540kW)	Generator No.3 power:1185kW
	(300kW)	Generator No.4 power: 1185kW proportional distribution
	WLG	
	WI G1 G2 G3 G4 G5	
(9)	WHG (1500kW)	(9) Total load increases by linkage operation of power
Power receiving and	WMG (1000) W)	receiving and four generators.
tour generators.	(TZUUKW)	If WHI (540kW) + WHG (1500kW) $\times$ 4 (set) = 6540kW is exceeded,
		A next number machine start command outputs after IS
	(540kW)	secona.
	WMI 1	
	(300kW)	Cancel is $6420kW$ $\left(\frac{WHI+WMI}{WHC}+WHCX4\right)$
	WI G1 G2 G3 G4 G5	
(10)		1 The load assignment after linkage of power receiving and
Power receiving and	1248kW (1500kW)	five generators.
five generators.	(1200kw)	Receiving power : WMI(300kW) Constant control
		Generator No.1 power:1248kW
	WHI WHI	Generator No.2 power:1248kW
	(540kW)	Generator No.3 power:1248kW
	(300kW)	Generator No.4 power:1248kW
	WLG	Generator No.5 power: 1248kW proportional distribution
(11)	WI G1 G2 G3 G4 G5	Tatal land immersion by Linkson anomatics of
(  ) Demok keesiwing and	(1500kW)	U lotal load increases by linkage operation of power
five generators	WMG (1200LW)	receiving and rive generators.
TIVE Bellerators.	(1200kw)	II WHI (340KW) $\pm$ WKG (1300KW) $\wedge$ 3 (Set) $-$ 0040KW IS exceeded.
		shares the remaining load
	(540kw)	טומו לא נווכ ו כוומו ווווא וטמע.
	(WM1 us	$\langle Caution \rangle$ The above is the case where it is set as WPG=WHG
	(JUUKW)	In case of WRG>WHG it becomes WRG constant
	WI G1 G2 G3 G4 G5	control.

• Separation and distribution control (Generator heavy burden operation mode)

Operation quantity	Load distribution state			ion st	ate	Control value	
(12) Power receiving and				WHG (1500kW) WMG	12 Total load decreases by linkage operation of power receiving and five generators.		
five generators.						(1200kW)	If below WHI (540kW) $-\Delta M$ (60kW) $+$ WHG (1500kW) $\times$ 4 (set) = 6480kW An operation order is the last generator (with
	WH1 (540kW)-						generator in operation), separation control is started
	(300kW) -						
			G1 G2	G3 (		<u></u> WLG	Cancel is 6510kW $\left( WHI - \frac{\Delta M}{2} + WHG \times 4 \right)$
(13) Power receiving and						WHG (1500kW)	③ The load assignment after one generator separation. Receiving power : 480kW
four generators.						(1200kW)	Generator No.1 power: 1500kW
	480kW \						Generator No. 2 power : 1500kW
	WHI (540kW)						Generator No.3 power: 1500kW proportional distribution
	(300kW) -						
	_		01 00			WLG	
(14)		<u></u>		63 (		WHG (1500kW)	Total load decreases by linkage operation of power
Power receiving and				/1170	)kW	WMG	receiving and four generators.
four generators.						(1200kw)	If below WHI (540kW) $-\Delta M$ (60kW) $+$ WHG (1500kW) $\times$ 3 (set) =
	WHI						generator in operation). separation control is started
	(540kW) <sup>-</sup>						after TB second.
	(300kW)	-				WI G	
	_	WI	G1 G2	G3 (	64 G5	+"-"	$cancel is bullow [WHI - 2 + WHG \times 3]$

Operation quantity	Load distribution state	Control value
(15) Power receiving and four generators.	480kW WH (1500kW) WM (1200kW) WM (1300kW) WM (1300kW) WLG	<ul> <li>The load assignment after one generator separation. Receiving power : 480kW</li> <li>Generator No. 1 power: 1500kW</li> <li>Generator No. 2 power: 1500kW</li> <li>Generator No. 3 power: 1500kW proportional distribution</li> </ul>
(16) Power receiving and three generators.	WH I (540kW) (300kW) (300kW) (300kW) (1060kW (1200kW) (12	(6) Total load decreases by linkage operation of power receiving and three generators. If below WHI (540kW) - $\Delta$ M (60kW) + WHG (1500kW) × 2 (set) = 3480kW. An operation order is the last generator (with generator in operation), separation control is started after TB second.
(17) Power receiving and two generators.	480kW WH I (540kW) WM I (300kW) WH I (300kW) WH I (100kW) WH I (100kW) (100k	<ul> <li>The load assignment after one generator separation. Receiving power : 480kW Generator No. 1 power : 1500kW Generator No. 2 power : 1500kW proportional distribution</li> </ul>
(18) Power receiving and two generators.	WH I         WH G         WH G         WH G           (1200kW)         WH G         WH G         WH G	(18) Total load decreases by linkage operation of power receiving and two generators. If below WHI (540kW) $-\Delta M$ (60kW) + WHG (1500kW) × 1 (set) = 1980kW. An operation order is the last generator (with generator in operation), separation control is started after TB second.
(19) Power receiving and one generators.	WI         G1         G2         G3         G4         G5           WH         G1         G2         G3         G4         G5           WHG         (1500kW)         WHG         (1200kW)           WHI         (540kW)         WHG         (1200kW)           WHI         (300kW)         WLG         WLG	Cancel is 2010kW (WHI - <u>2</u> + WHG×1) <sup>(19)</sup> The load assignment after one generator separation. Receiving power : 480kW Generator No. 1 power : 1500kW proportional distribution
(20) Power receiving and one generators.	WHG (1500kW) (1200kW) (1200kW) (1200kW) (1200kW) (1200kW) (1200kW) (1200kW) (1200kW) (1200kW) (1200kW) (1200kW)	Total load decreases by linkage operation of power receiving and one generator. If below WHI (540kW) $-\Delta M$ (60kW) =480kW. Separation control of the last generator is started after TB second. Cancel is 510kW (WHI $-\frac{\Delta M}{2}$ )
(21) Power receiving only	WI         G1         G2         G3         G4         G5           (1500kW)         WHG (1200kW)         WHG (1200kW)         WHG (1200kW)           WHI (300kW)         G1         G2         G3         G4         G5	② Load after a generator separation. Receiving power∶480k₩

• Starting and distribution control (Individual operation mode)

Operation quantity	Load distribution state	Control value
(1) One generator	WHG (1500KW) WMG (1200kW)	<ul> <li>⑦ Generator load increases by operation of one generator. If next machine starting power "WHG(1500kW) - deviation △H(300kW) = 1200kW" is exceeded. Start command outputs to next machine.</li> </ul>
	WMI (300KW) WI 61 62 63 64 65	Cancel is 1050kW $\left(\frac{WHG + WMG}{2} - \Delta H\right)$
(2) Two generators	WHG (1500kW) WMG (1200kW) (540kW)	② The load assignment after linkage of two generators. Generator No. 1 power: 600kW Generator No. 2 power: 600kW proportional distribution
	WILG WILG	
(3) Two generators	WHG (1500kW) WMG (1200kW) (1200kW)	<ul> <li>③ Total load increases by linkage operation of two generators.</li> <li>If next machine starting power "WHG(1500kW) - deviation ∆H(300kW) ×2(set) =2400kW" is exceeded. Start command outputs to next machine.</li> </ul>
	(300kw) WI 61 62 63 64 65	Cancel is 2100kW $\left(\left(\frac{WHG+WMG}{2}-\Delta H\right)\times 2\right)$
(4) Three generators	WHG (1500kW) WMG (1200kW) WHI	<ul> <li>The load assignment after linkage of three generators. Generator No. 1 power: 800kW Generator No. 2 power: 800kW Generator No. 3 power: 800kW proportional distribution</li> </ul>
	(540kW) (300kW) WI 61 62 63 64 65	
(5) Three generators	(1500kW) WH I (540kW) WH I	<ul> <li>⑤ Total load increases by linkage operation of three generators.</li> <li>If next machine starting power "WHG(1500kW) - deviation △H(300kW) × 3 (set) = 3600kW" is exceeded.</li> <li>Start command outputs to next machine.</li> </ul>
	(300kW) WI 61 62 63 64 65	Cancel is 3150kW $\left( \left( \frac{WHG + WMG}{2} - \Delta H \right) \times 3 \right)$
(6) Four generators	WHG (1500kW) WMG (1200kW) (1200kW) (1200kW) WMI (300kW) WMI	(6) The load assignment after linkage of four generators. Generator No. 1 power : 900kW Generator No. 2 power : 900kW Generator No. 3 power : 900kW Generator No. 4 power : 900kW proportional distribution
(7)	WI 61 62 63 64 65 WHG	⑦ Total load increases by linkage operation of four
Four generators	(1300KW) WMG (1200KW) (1200KW)	generators. If next machine starting power "WHG(1500kW) — deviation $\Delta$ H(300kW) ×4(set) = 4800kW" is exceeded. Start command outputs to next machine.
	(300kw) WI 61 62 63 64 65	Cancel is 4200kW $\left( \left( \frac{WHG + WMG}{2} - \Delta H \right) \times 4 \right)$

Operation quantity	Load distribution state	Control value
(8) Five generators	WH1 (540kW)         WH6 (1500kW)           WH1 (300kW)         WH6 (1200kW)           WH1 (300kW)         WH6 (1200kW)	<ul> <li>The load assignment after linkage of five generators. Generator No. 1 power : 960kW Generator No. 2 power : 960kW Generator No. 3 power : 960kW Generator No. 4 power : 960kW Generator No. 5 power : 960kW proportional distribution</li> </ul>
(9) Five generators	1650kW         WHG (1500kW)           WHI (540kW)         WHG (1200kW)           WHI (300kW)         WI WHI (300kW)	(9) Total load increases by linkage operation of five generators. If 110% of the generator power WRG(1500kW) is exceeded, a generator over load is detected and light trouble output is done.

• Separation and distribution control (Individual operation mode)

Operation quantity	Load distribution state	Control value
(10)		① Total load decreases by linkage operation of five
Five generators	(TSUUKW)	generators.
		If below "Generator separation possible power
	720kW	WMG(1200kW) - Deviation $\Delta H(300kW) \times 4$ (set) = 3600kW".
		An operation order is the last generator (with generator
	(540kW)	in operation), separation control is started after TB
	(2001-W)	second.
	(300kW)	
	WI G1 G2 G3 G4 G5	Cancel is 4200kW $\left[\left(\frac{-WHO+WWO}{2} - \Delta H\right] \times 4\right]$
(11)		${f I}$ The load assignment after one generator separation.
Four generators	WMG	Generator No.1 power:900kW
	900kW (1200kW)	Generator No.2 power:900kW
		Generator No.3 power:900kW
	WHI I I I I I I I I I I I I I I I I I I	Generator No.4 power:900kW proportional distribution
	(540kW)	
	(300kW)	
	WI G1 G2 G3 G4 G5	
(12)	WHG	② Total load decreases by linkage operation of four
Four generators	(1500KW)	generators.
	(1200kW)	If below "Generator separation possible power
	. 675kW	WMG(1200kW) - Deviation $\Delta H(300kW) \times 3(set) = 2700kW$ ".
		An operation order is the last generator (with generator
	(540kW)	in operation), separation control is started after TB
	(300km)	second.
	(000K#/	( WHG+WMG) .)
	WI G1 G2 G3 G4 G5	Cancel is 3150kW $\left[\left(\frac{-\Delta H}{2} - \Delta H\right] \times 3\right]$
(13)		③ The load assignment after one generator separation.
Three generators	WMG	Generator No.1 power:900kW
	900kW (1200kW)	Generator No.2 power:900kW
		Generator No.3 power:900kW proportional distribution
	WHI	
	(540kW)	
	(300kW)	
	WLG	
	'WI 'G1 'G2 'G3 'G4 'G5 '	

Operation quantity	Load distribution state	Control value		
(14)		(4) Total load decreases by linkage operation of three		
Three generators	WMG	generators.		
	(1200kW)	If below "Generator separation possible power		
	. COOLW	WMG(1200kW) - Deviation $\Delta H(300kW) \times 2(set) = 1800kW$ ".		
	WHI W	An operation order is the last generator (with generator		
	(540kW)	in operation), separation control is started after TB		
	(300kW) <sup>-</sup>	second.		
	WI G1 G2 G3 G4 G5	Cancel is 2100kW $\left( \left( \frac{-WHG + WMG}{2} - \Delta H \right) \times 2 \right)$		
(15)		⑮ The load assignment after one generator separation.		
Two generators	WMG	Generator No.1 power:900kW		
	900kW (1200kW)	Generator No.2 power:900kW proportional distribution		
	(540kW)			
	WMI			
	(300kW)			
	WI 61 62 63 64 65			
(16)	WHG	© Total load decreases by linkage operation of two		
Two generators	(1500kW)	generators.		
		If below "Generator separation possible power		
		WMG(1200kW) - Deviation $\Delta H(300kW) \times 1$ (set) = 900kW".		
	WHI / 450kW	An operation order is the last generator (with generator		
	(540kW)	in operation), separation control is started after TB		
	(300kW) <sup>-</sup>	second.		
	WLG	Cancel is 1050kW $\left( \left( \frac{WHG + WMG}{-\Delta H} \right) \times 1 \right)$		
	WI G1 G2 G3 G4 G5			
(17)	(1500kW)	1 The load assignment after one generator separation.		
Une generators		Generator No. I power : 900kW		
	WHI			
	(540kw)			
	WM I (300kW)			
	WLG			
	WI G1 G2 G3 G4 G5			

8. Maintenance

#### 8.1 Error message

When displaying an error from error occurrence. The [b] key and the [a] key are simultaneously pushed 3 seconds or more in the state of display lighting. An error is not displayed if the error has not occurred.

Switching of an error display is possible by pushing the  $\left[ \text{DISPLAY} \right]$  key.

The error display of a maximum of ten items is displayed. (If the number of error occurrence is ten or less, it returns to No. 01 after displaying the number of occurrence.)



● Error of equipment (Er00~Er29)

No.	Error description	Control state	Trouble output	Error return condition	Note
Er00	ROM memory abnormality	Stop	Alarm	Not clear	Check enforcement at auxiliary power supply apply.
Er01	RAM memory abnormality	Stop	Alarm	Not clear	Check enforcement at auxiliary power supply apply.
Er02	A/D conversion abnormality	Stop	Light trouble	Auto reset	
Er03	Control set value abnormality (Set range combination error)	Stop	Light trouble	Data-corrects in key switch.	
Er04	Save set point abnormality (Set range combination error)	Stop	Alarm	Not clear	Check enforcement at auxiliary power supply apply.
Er05	Measurement reference value abnormality (Parity error)	Stop	Alarm	Not clear	Check enforcement at auxiliary power supply apply.
Er06					
Er07					
Er08					
Er09			(12)		
Er10	First machine communication data error.	Continuation	Light trouble	Auto reset	Error of continuation occurrence
Er11	Second machine communication data error.	Continuation	Light trouble	Auto reset	Error of continuation occurrence
Er12	Third machine communication data error.	Continuation	Light trouble	Auto reset	Error of continuation occurrence
Er13	Fourth machine communication data error.	Continuation	Light trouble	Auto reset	Error of continuation occurrence
Er14	Fifth machine communication data error.	Continuation	Light trouble	Auto reset	Error of continuation occurrence
Er15	Sixth machine communication data error.	Continuation	Light trouble	Auto reset	Error of continuation occurrence
Er16	Seventh machine communication data error	Continuation	Light trouble	Auto reset	Error of continuation occurrence
Er17	Eighth machine communication data error	Continuation	Light trouble	Auto reset	Error of continuation occurrence
Er18	First machine communication line error.	Continuation	Light trouble	Auto reset	Error of continuation occurrence
Er19	Second machine communication line error	Continuation	Light trouble	Auto reset	Error of continuation occurrence
Er20	Third machine communication line error	Continuation	Light trouble	Auto reset	Error of continuation occurrence
Er21	Fourth machine communication line error.	Continuation	Light trouble	Auto reset	Error of continuation occurrence
Er22	Fifth machine communication line error	Continuation	Light trouble	Auto reset	Error of continuation occurrence
Er23	Sixth machine communication line error	Continuation	Light trouble	Auto reset	Error of continuation occurrence
Er24	Seventh machine communication line error	Continuation	Light trouble	Auto reset	Error of continuation occurrence
Er25	Eighth machine communication line error	Continuation	Light trouble	Auto reset	Error of continuation occurrence
Er26					
Er27					
Er28					
Er29					

Note(12) Er10~Er25 The error of those other than a self-machine is only a display.

• Operation error of equipment (Er40~Er65)

No.	Error description	Control state	Trouble output	Error return condition	Note
Er40	Set combination error. $\Delta F$ and 25	Continuation	—	Error display is clear in SET SW.	Data are not received but are control-continued by the old data.
Er41	Set combination error. WFSI≧WRI	Continuation	—	Error display is clear in SET SW.	Data are not received but are control-continued by the old data.
Er42	Set combination error. WHI $\bigcirc -\Delta M \bigcirc -\Delta WI \bigcirc \ge WMI \bigcirc$ $\ge WLI \bigcirc +\Delta WI \bigcirc$	Continuation	_	Error display is clear in SET SW.	Data are not received but are control-continued by the old data.
Er43	Set combination error. WHI②-△M②-△WI②≧WMI② ≧WLI②+△WI②	Continuation	_	Error display is clear in SET SW.	Data are not received but are control-continued by the old data.
Er44	Set combination error. VT×CT≦9999	Continuation	_	Error display is clear in SET SW.	Data are not received but are control-continued by the old data.
Er45	Set combination error. VT×CT≧WRG①	Continuation	_	Error display is clear in SET SW.	Data are not received but are control-continued by the old data.
Er46	Set combination error. VT×CT≧WRG②	Continuation	—	Error display is clear in SET SW.	Data are not received but are control-continued by the old data.
Er47	Set combination error. WHG①-5%≧WMG①	Continuation	—	Error display is clear in SET SW.	Data are not received but are control-continued by the old data.
Er48	Set combination error. WHG②-5%≧WMG②	Continuation	—	Error display is clear in SET SW.	Data are not received but are control-continued by the old data.
Er49	Set combination error. THW≧TLW	Continuation	_	Error display is clear in SET SW.	Data are not received but are control-continued by the old data.
Er50	Set combination error. THF≧TLW	Continuation	_	Error display is clear in SET SW.	Data are not received but are control-continued by the old data.
Er51	Set combination error. ∆WTRG≧∆WTHG≧∆WG①	Continuation	—	Error display is clear in SET SW.	Data are not received but are control-continued by the old data.
Er52	Set combination error. ∆WTRG≧∆WTHG≧∆WG②	Continuation	—	Error display is clear in SET SW.	Data are not received but are control-continued by the old data.
Er53	Set combination error. THQ≧∆TLQ	Continuation	—	Error display is clear in SET SW.	Data are not received but are control-continued by the old data.
Er54					
Er55					
Er56					
Er5/					
Er50					
Er60	Address set mistake.	Stop	Light trouble	Power supply reset after correction	Machine interval set mistake.
Er61	Start input mistake.	Stop	Light trouble	Auto reset	
Er62	Lead generator designation mistake.	Continuation	Light trouble	Auto reset	Address 1 priority to nothing.
Er63	Power receiving constant control value designation mistake	Continuation	Light trouble	Auto reset	Control by lead machine data. (Only in lead machine and self- machine distribution)
Er64	Address change mistake.	Continuation	Light trouble	Auto reset	Change address for power-up.
Er65					

• Error of generator circumference and generator (Er70~Er95)

No.	Error description	Control state	Trouble output	Error return condition	Note
Er70	Bus voltage control range outside	Stop	Light trouble	Auto reset	Error LED turn on the light.
Er71	Generator voltage range outside	Stop	Light trouble	Auto reset	Error LED turn on the light.
Er72	Bus frequency range outside	Stop	Light trouble	Auto reset	Error LED turn on the light.
Er73	Generator frequency range outside	Stop	Light trouble	Auto reset	Error LED turn on the light.
Er74	Frequency difference control range outside	Stop	Light trouble	Auto reset	Error LED turn on the light.
Er75					
Er76					
Er77	Synchronous closing mistake	Closing output stop	Alarm	Possible at the auto synchronous start OFF. Return, Restart.	ΔV, ΔF control. Synchronous check output continuation.
Er78	Governor system abnormality	Continuation	Light trouble	Auto reset	They are possible by set detection cancellation.
Er79	AVR system abnormality	Continuation	Light trouble	Auto reset	
Er80	Power receiving transducer input disconnection	Stop	Light trouble	Auto reset	W transducer input OmA 5 seconds
Er81	Power receiving reverse power	Continuation	Light trouble	Auto reset	Less than OkW 10 seconds
Er82	Generator over load	Continuation	Light trouble	Auto reset	With no detection timer
Er83					
Er84					
Er85					
Er86					
Er87					
Er88					
Er89					
Er90					
Er91					
Er92					
Er93					
Er94					
Er95					

# 8.2 Trouble shooting

No.	Abnormal phenomenon	Probable cause		Measures	
	POWER LED does not	Power	supply is not applied	Check of power supply	
1	turn on the light	Fauin	ment trouble	Equipment replacement	
		ErOO ROM memory abnormality			
		Er01	RAM memory abnormality	Equipment error.	
			A/D conversion chnormality	Equipment replacement.	
		Eruz			
		Er03	Control set value abnormality	Control data apnormality,	
				Re-setting.	
		Er04	Save set point appormanity		
			(Set range combination error)	Equipment error.	
		Fr05	Measurement reference value abnormality	Equipment replacement.	
		2100	(Parity error)		
		Er10			
		5	Each machine communication data error.	Abnormal check of communication circuit.	
		Er17			
		Er18		Abnormal check of communication circuit.	
		(	Each machine communication line error.	Check of parallel operation number set mistake, or address set mistake.	
		,			
		Er25			
		Er40	Set combination error. $\Delta F$ and 25		
		Er41	Set combination error. WFSI≧WRI		
		Er12	Set combination error.		
		L142	$\mathbb{W} = \mathbb{W} = $		
		Er12	Set combination error.		
		Er43	$\mathbb{W}H\mathbb{Q}-\Delta\mathbb{M}\mathbb{Q}-\Delta\mathbb{W}\mathbb{Q}\cong\mathbb{W}H\mathbb{Q}\cong\mathbb{W}L\mathbb{Q}+\Delta\mathbb{W}\mathbb{Q}$		
	Error in displayed	Er44	Set combination error. VT×CT≦9999		
		Er45	Set combination error. VT×CT≧WRG①	Set data abnormality, Re-setting.	
		Er46	Set combination error. VT×CT≧WRG②		
		Er47	Set combination error. WHG①−5%≥WMG①		
		Er 48	Set combination error. WHG②-5%≧WMG②		
		Er 10	Set combination error THW≥TLW		
		Er 50	Set combination error THE>TLW		
2	$(E_r 0 0 \sim E_r 2)$	Er61	Set combination error $AWTRC>WTHC>AWC(1)$		
	(Er00~Er82)	ErE2	Set combination error $\Delta WTPC > WTUC > \Delta WCO$		
		Er52	Set combination error. THOSTIO		
		Er00	Address set mistake	Address sverler De setting	
		LIOU	Aduress set mistake.	Audress Overlap. Ne setting.	
			Ctart input mictaka	input Offering start and faread	
		Er61		appreciation aimultaneous input	
				Separation Simultaneous Input.	
				Setting switch on and synchronous	
				Simultaneous input. Defete of one side.	
		Er62	Lead generator designation mistake.	Designated overlap (3 or more sets)	
				WILLI NO DESIGNATION. Re-Setting.	
		F 00	Power receiving constant control value	It is a set value disagreement between	
		Er63	designation mistake	machines from distribution control.	
		F 70		All machine uniformity value re-setting	
		Er/0	Bus voltage control range outside	Check of voltage input value.	
		Er/1	Generator voltage control range outside.		
		Er72	Bus frequency control range outside.		
		Er73	Generator frequency control range outside.	Check of input frequency.	
		Er74	Frequency difference control range outside.		
		Er77	Synchronous closing mistake	25 output. Check of circumference of	
				circuit breaker	
		Er78	Governor system abnormality.	Check of governor system.	
		Er79	AVR control system abnormality.	Check of AVR control system.	
		E~00	Power receiving transducer input	Charle of nowar transducar and wighter	
		ErŏU	disconnection	check of power transducer and wiring.	
		Er01	Demok koopining konstant power	Loaded condition check. Quality judging	
		Ergi	rower receiving reverse power	of power receiving set value.	
		F 00	Generator over load.	Loaded condition check. Quality judging	
		E182	(Power, Reactive power)	of generator set value.	

No.	Abnormal phenomenon	Probable cause	Measures
с С	No control begins. (However, automatic synchronous closing control is excluded)	Control start input is not applied.	Check of control starts input.
5		Equipment trouble.	Equipment replacement.
4	Automatic synchronous	Synchronous start input is not applied.	Check of synchronous starts input.
	closing does not begin.	Equipment trouble.	Equipment replacement.
5	Control of power receiving does not begin.	Power receiving start is not inputted.	Check of power receiving start input.
		Equipment trouble.	Equipment replacement.
6	Distribution control does not begin.	Control start, distribution start is not inputted.	Check of control start input, distribution start input.
		Setting of function change switch (ALS, APFR, ALS+APFR) is not right.	Check of function change switch (ALS or ALS+APFR select)
		Equipment trouble.	Equipment replacement.
7	Power-factor control does not begin.	Power receiving start and distribution start is not inputted.	Check of control start input, distribution start input.
		Setting of function change switch (ALS, APFR, ALS +APFR) is not right.	Check of function change switch (APFR or ALS+APFR select)
		Equipment trouble.	Equipment replacement.
8	Order of operation is not right. (Start command does not output)	Order of operation is not right. (Omission, overlap)	Re-setting of operation order.
	Voltage does not balance. (∆V LED does not turn on the light.)	If 90R and 90L output. Fault of AVR system.	Check of AVR system.
9		If 90R and 90L don't output. Eequipment trouble.	Equipment replacement.
10	Frequency does not balance. ( $\Delta F$ LED does not turn on the light.)	lf 65R and 65L output. Failure of governor system.	Check of governor system.
		If 65R and 65L don't output. Equipment trouble.	Equipment replacement.
11	Closing signal does not output. (25 LED does not turn on the light)	Closing conditions are not met.	Check of closing condition. (Check of ΔV, ΔF)
		It is equipment trouble if closing conditions are met.	Equipment replacement.
10	Synchronous check signal does not output.	$\Delta V$ and $\Delta F$ have not come in the regulation value.	Check of $\Delta V$ , $\Delta F$ .
12		Equipment trouble.	Equipment replacement.
12	Alarm is outputted.	Synchronous closing mistake.(Er77)	Check of circuit breaker system.
13		Set point abnormality. (ErO4)	Equipment replacement.
14	Light trouble is outputted.	Error occurrence	Check of error code. Individual correspondence.
15	Setting by the key switch cannot be performed.	The setting permission switch does not constitute ON.	Setting permission switch is set to ON.
		Synchronous start is ON	The setting synchronously controlling is impossible.
		Equipment trouble.	Equipment replacement.

#### 8.3 Maintenance

- (1) About the life of an aluminium electrolytic condenser. If par temperature of the installation environment of AGC-300 is made into 40°C, the life of an aluminium electrolytic condenser becomes about 11 years by the shortest.
  Description of the used of the used of this product exceed 11 years
  - Replacement repair is needed if the usable years of this product exceed 11 years.
- (2) Check
  - Please check the next item periodically.
  - ① Does power supply LED light?
  - ② ERROR LED, ALARM LED (alarm output), LIGHT TROUBLE LED. Does not LED light?
  - ③ Have not other light emitting diodes or Numbers light emitting diode given the abnormal display?

product is disassembled/remodeled, in case of false operation by customer, etc.) is beyond our warranty.

- ④ Aren't there slack of wiring and slack of a captive screw?
- ⑤ Has not dust adhered to the case or the terminal? Please remove, if it has adhered.

8.4 Measures at trouble

As our principle, we recall product in question and repair it. If judged as product failure, have a contact with us or sales agent for repairing work (Also have a contact with us or sales agent for specification change). Product failure which we are not responsible for (When responsibility in manufacturing process is not recognized, when

 $\Theta$  DAIICHI ELECTRONICS CO., LTD.

Head Office : 11-13 Hitotsuya 1-chome, Adachi-ku, Tokyo, 121-8639 Japan. Phone: 03-3885-2411 , Fax: 03-3858-3966

Kyoto Office : 1-19 Ichinobe-Nishikawahara, Jyoyou-shi, Kyoto, 610-0114 Japan. Phone: 0774-55-1391 , Fax: 0774-54-1353

Revision D, DATE: June 29, 2007